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Lighten Everyone's Load: LIDAR Applications to Support Engineers, Planners, Scientists and More

Michael J. Olsen
Oregon State University

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Lighten Everyone's Load:

Lidar Applications to Support engineers, planners, scientists, and more

Michael J. Olsen
Assistant Professor, Geomatics
School of Civil and Construction Engineering
Oregon State University



Portland State University TREC Seminar
May 8, 2015



Michael J. Olsen, PhD, E.I.T.

**Assistant Professor of Geomatics
School of Civil and Construction Engineering
Oregon State University**

**PhD. University of California, San Diego
Research: Lidar to model and analyze seacliff erosion**

MS and BS, University of Utah, liquefaction hazard mapping

**Primary Research Interests:
Lidar, 3D modeling, scientific visualization, computer programming,
Coastal geomorphology, geohazard engineering, Geographic
Information Systems**

Civil & Construction Engineering Geomatics Faculty at OSU



Robert Schultz
Professor, 1962



Tracy Arras
Senior Instructor, 2003



Mike Olsen
Assistant Professor, 2009



Dan Gillins
Assistant Professor,
2013



Christopher Parrish
Associate Professor
2014

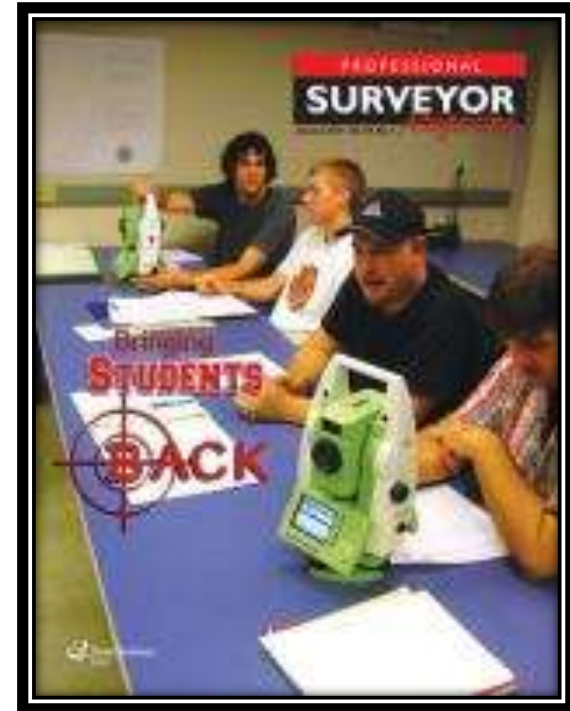


Jihye Park,
Assistant Professor,
2015

Oregon State
UNIVERSITY

Many additional geospatial faculty in other departments

Industry Partnership

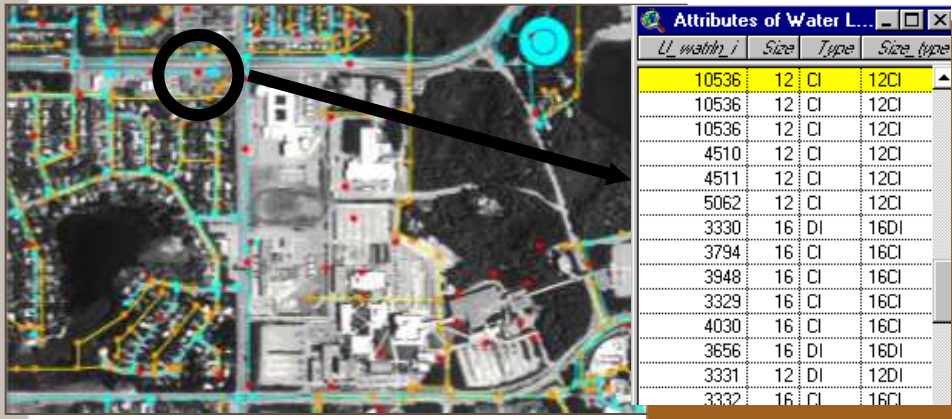


- Recruit top students
- Expand course work and research to reflect industry advances
- Keep surveying as an integral part of our Civil Engineering program
- Provide the latest equipment, software, and workflows
- Prepare students to become licensed surveyors
- Produce work-ready graduates

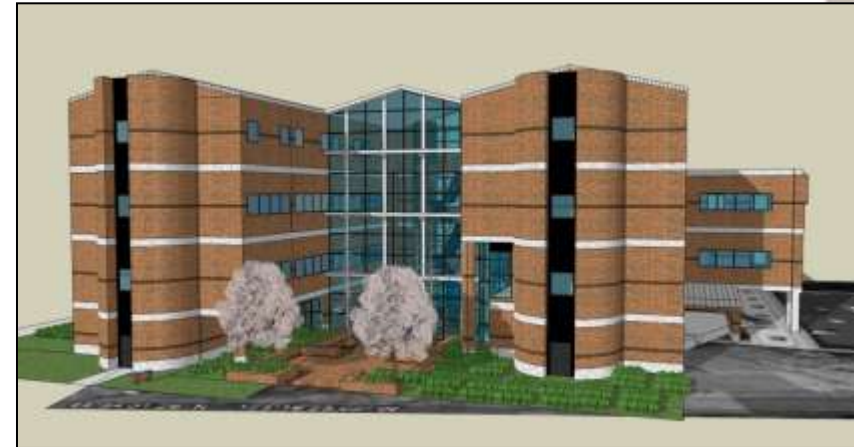
Courses and Graduate Research!



Courses and Graduate Research!



GIS - Municipal Utility System



3D information modeling



LIDAR, SFM, & 3D, Virtual Reality



Property Surveying

Outline

- What is LIDAR?
- How does it work?
- How is it used?
- What is in store in the future?

Lidar (Laser Scanning)

Light Detection and Ranging

Active System

Laser Range

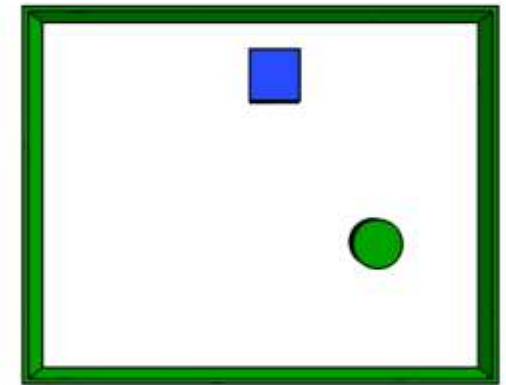
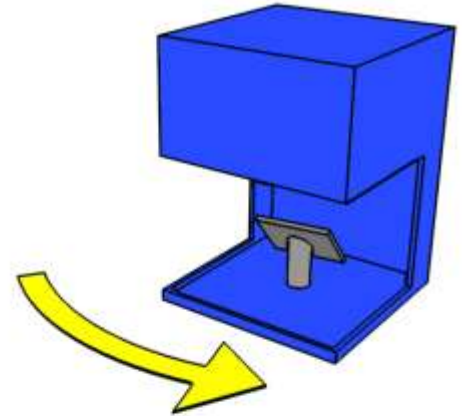
Single/Multiple Returns

Angle Determination

3D Point Cloud

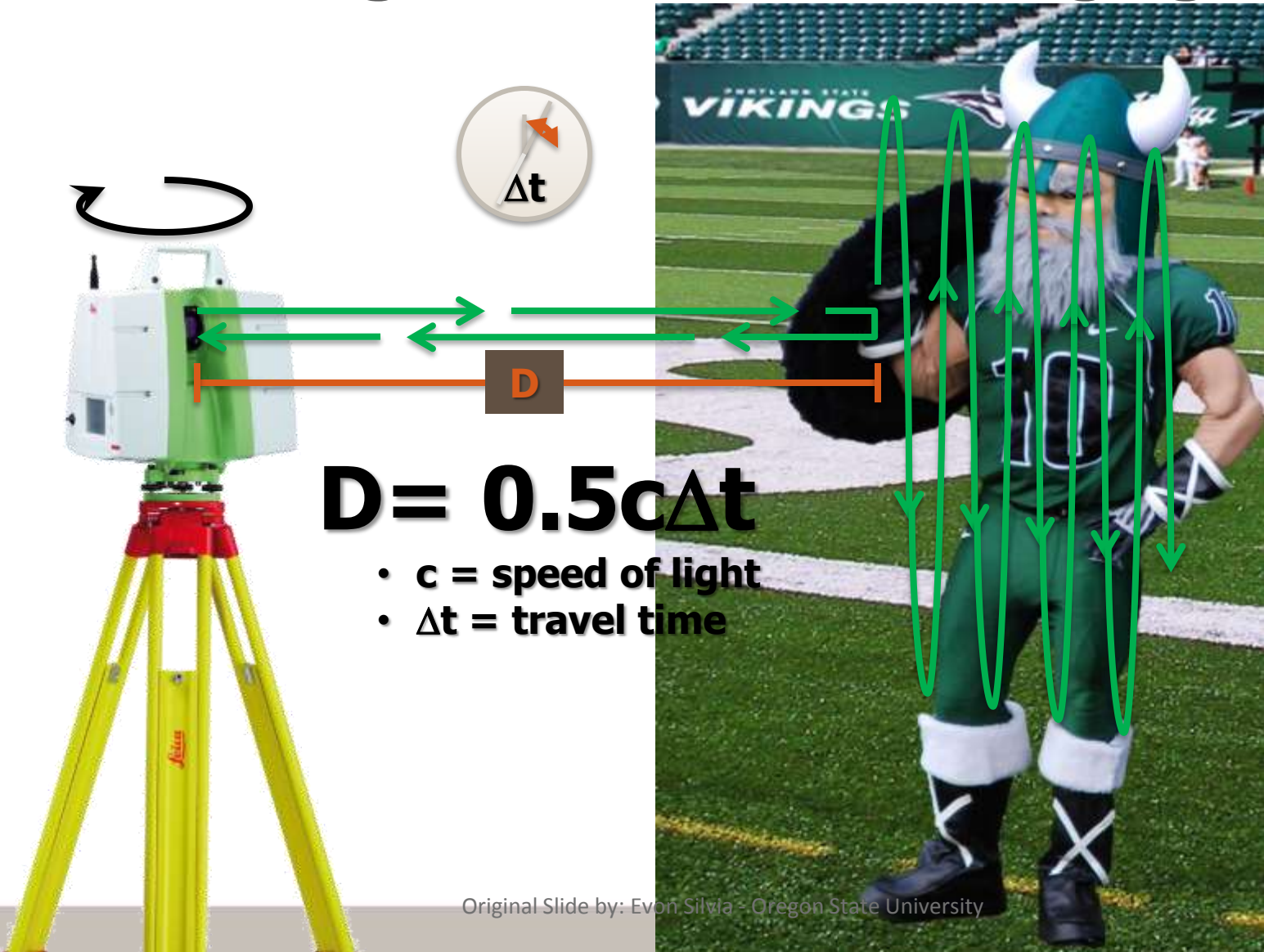
Intensity

RGB Color



What is Lidar?

LiDAR = Light Detection and Ranging



LiDAR Rap v1.0 by M\$lice

LiDAR relies on Line of Sight
Using pulses of light,
But not too bright,
It calculates the Time of Flight
And can be done in da nite
Works from the ground or during da flight,
Gives you da heightz,
Requires lots of bytes,
Objects in the way give you a blight,
Don't have fright
We'll learn you how to avoid plight,
So it gits da job done right!
With data dat can fit your control nice n tight!



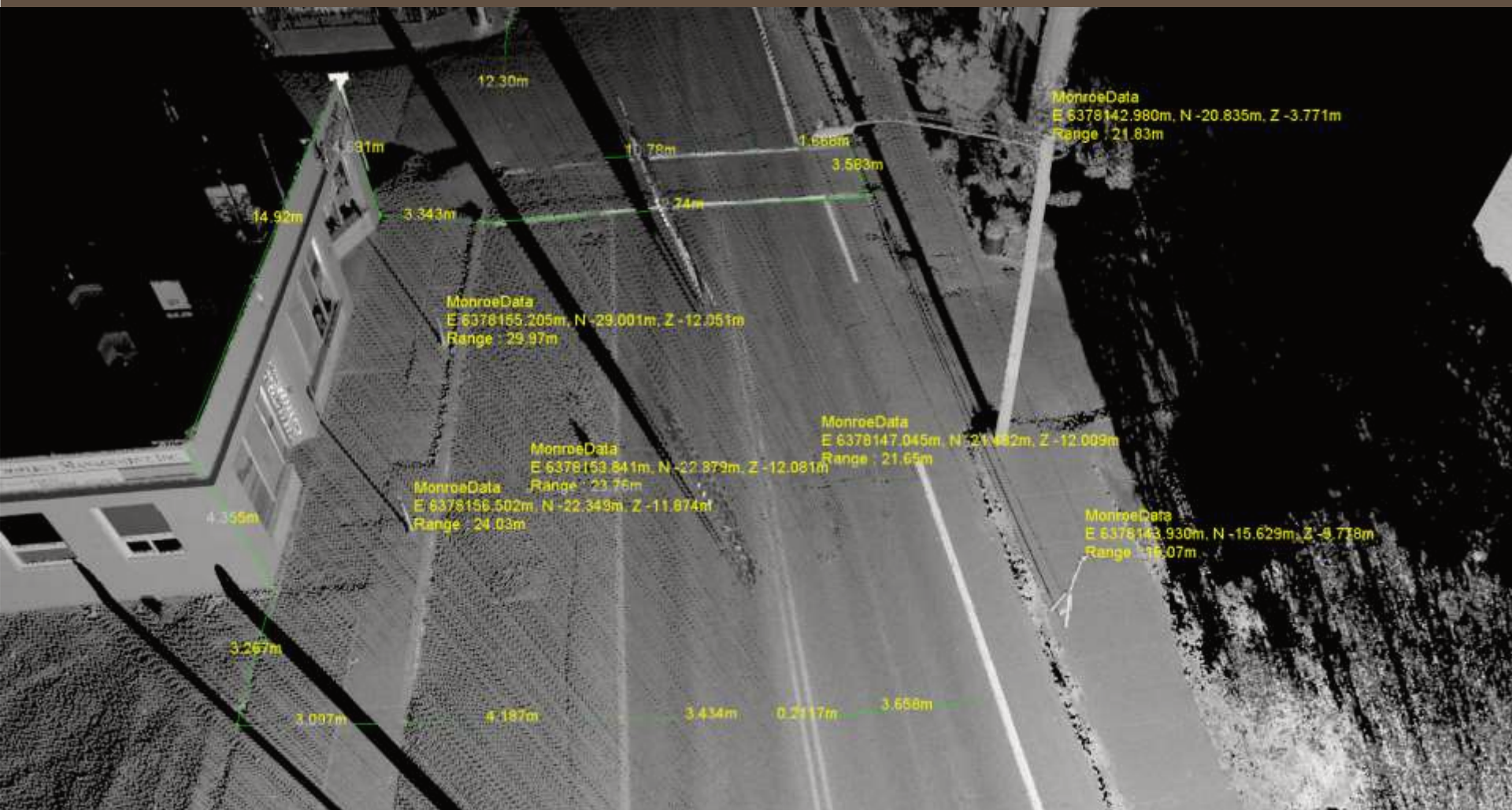
Magic School Bus LIDAR

Oregon State
UNIVERSITY

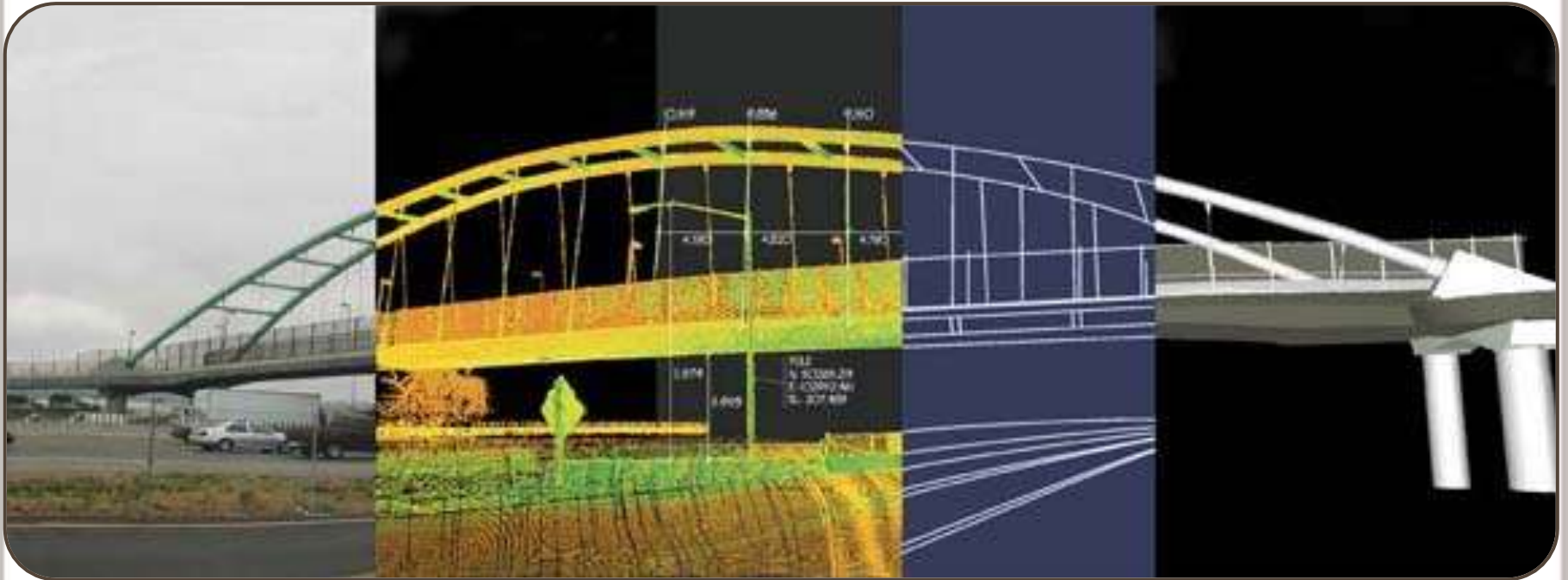
Point Cloud



Measurements



Static Scanning Products



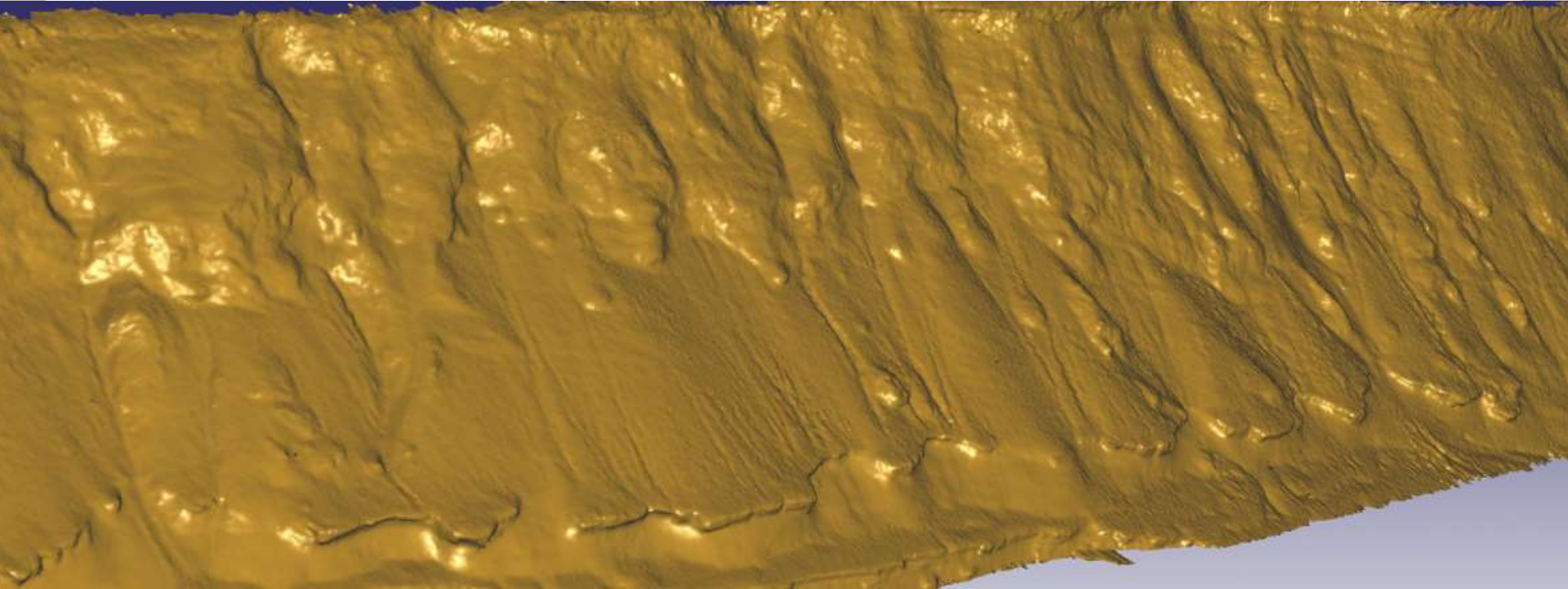
Photo

Scan

Vector

Solid Objects

3D surface modeling



Multiple Returns

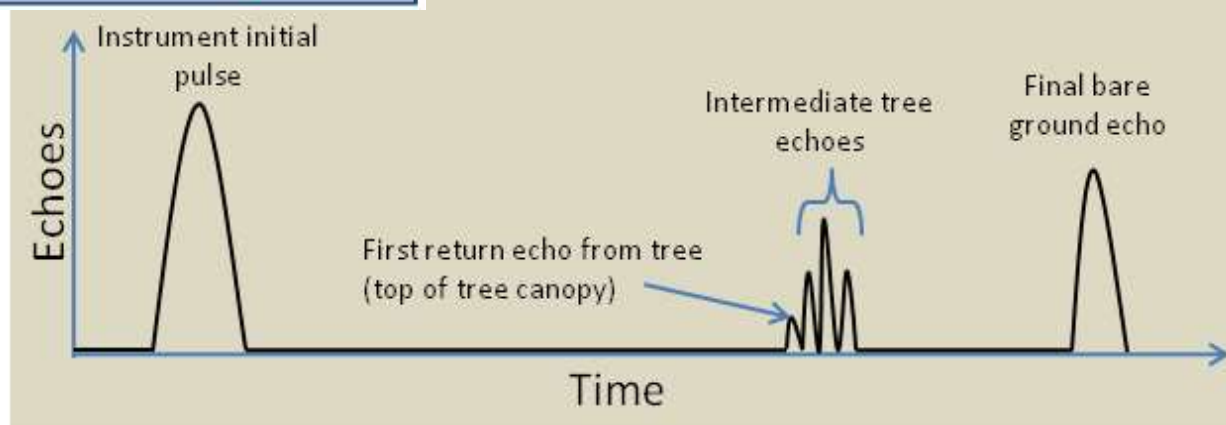
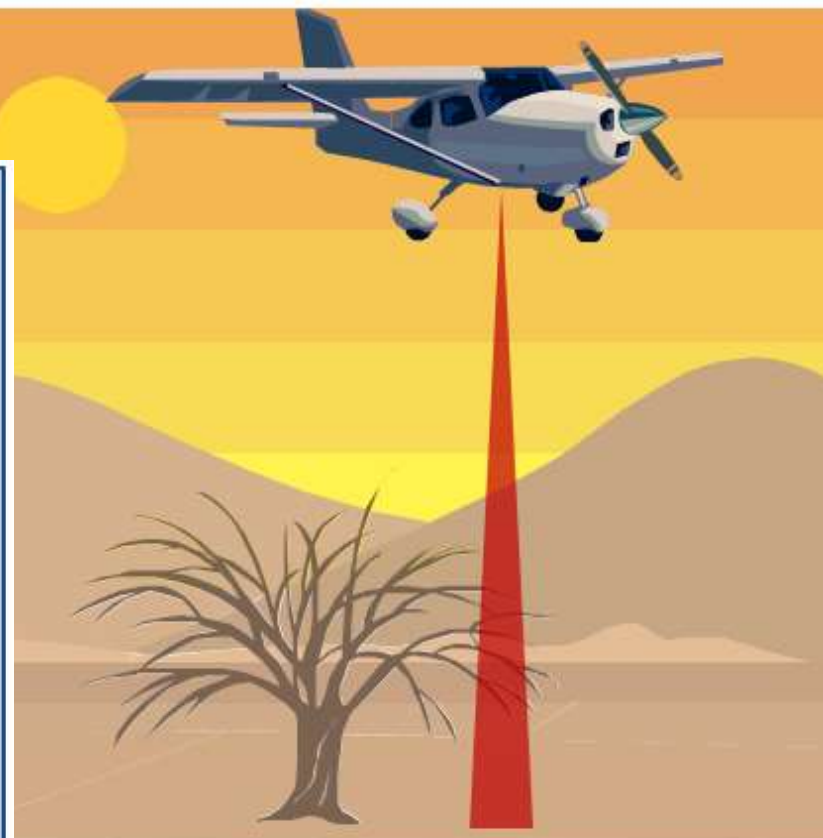
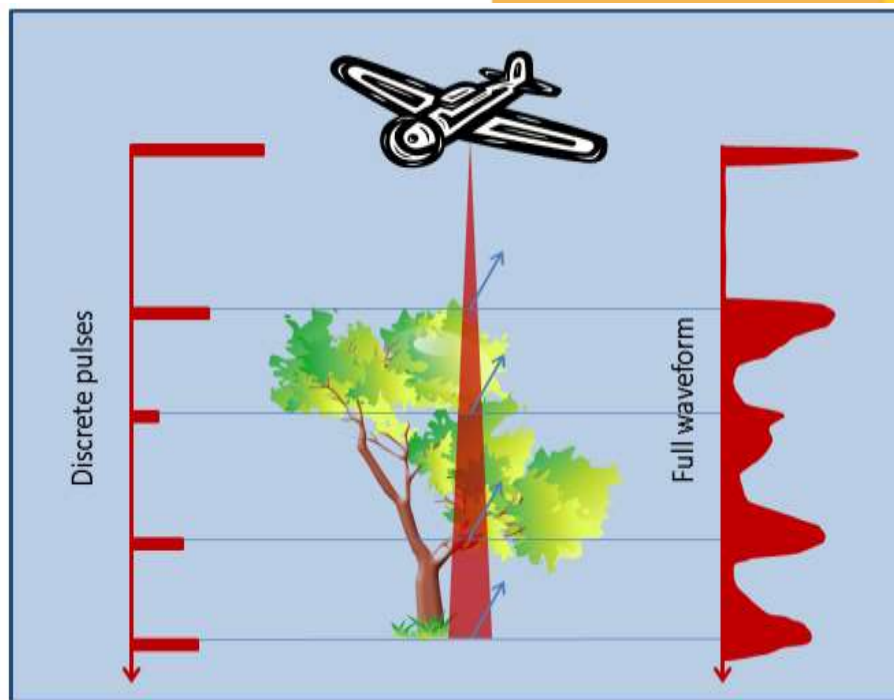
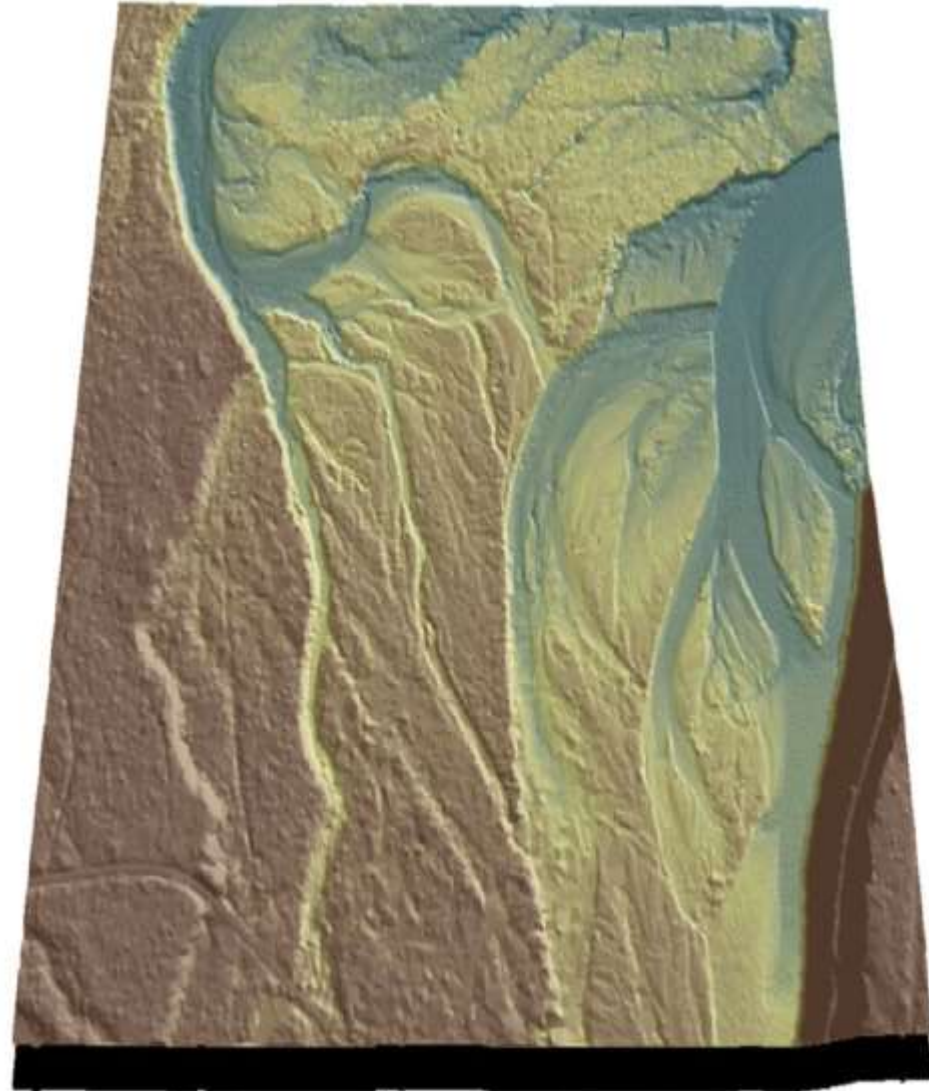
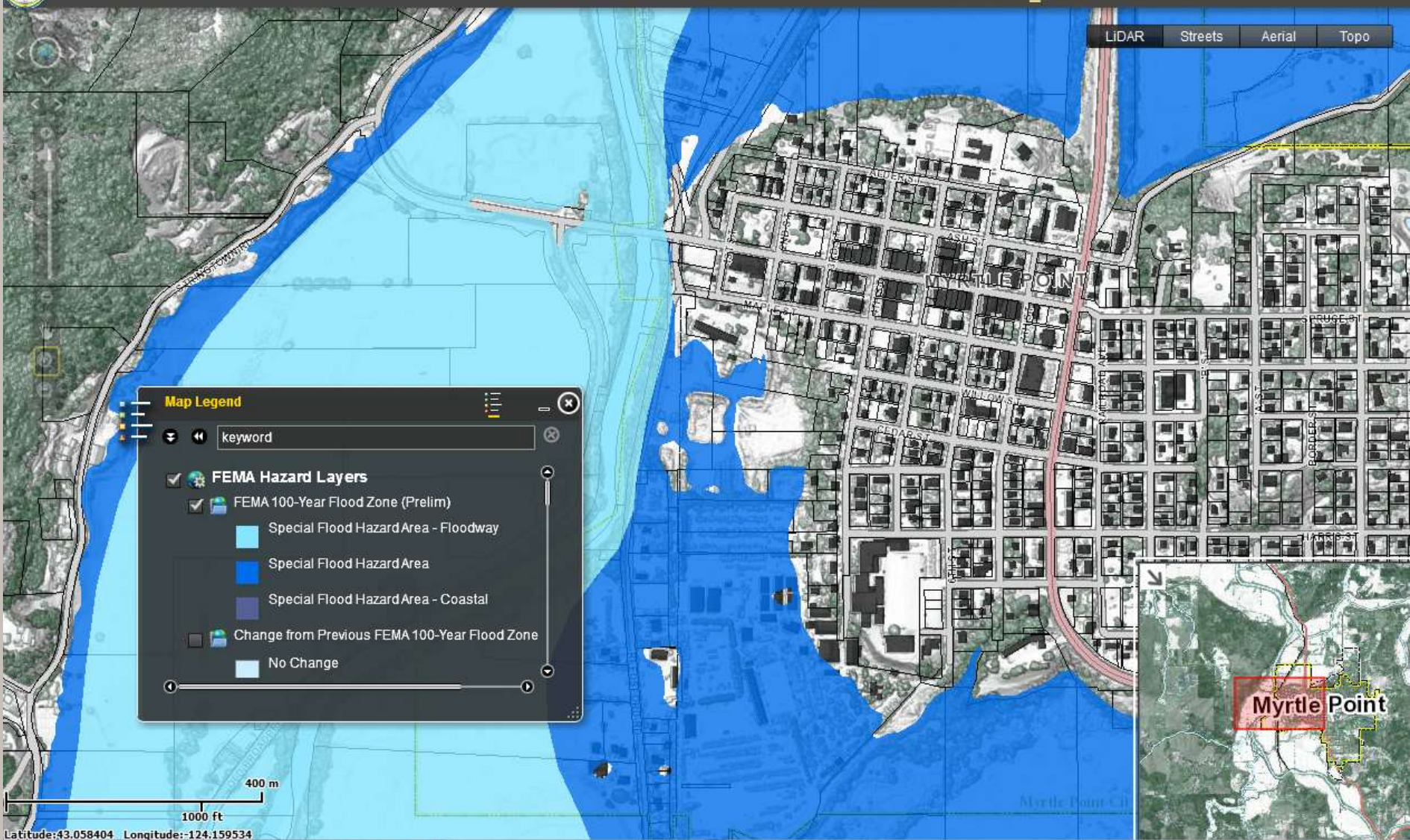
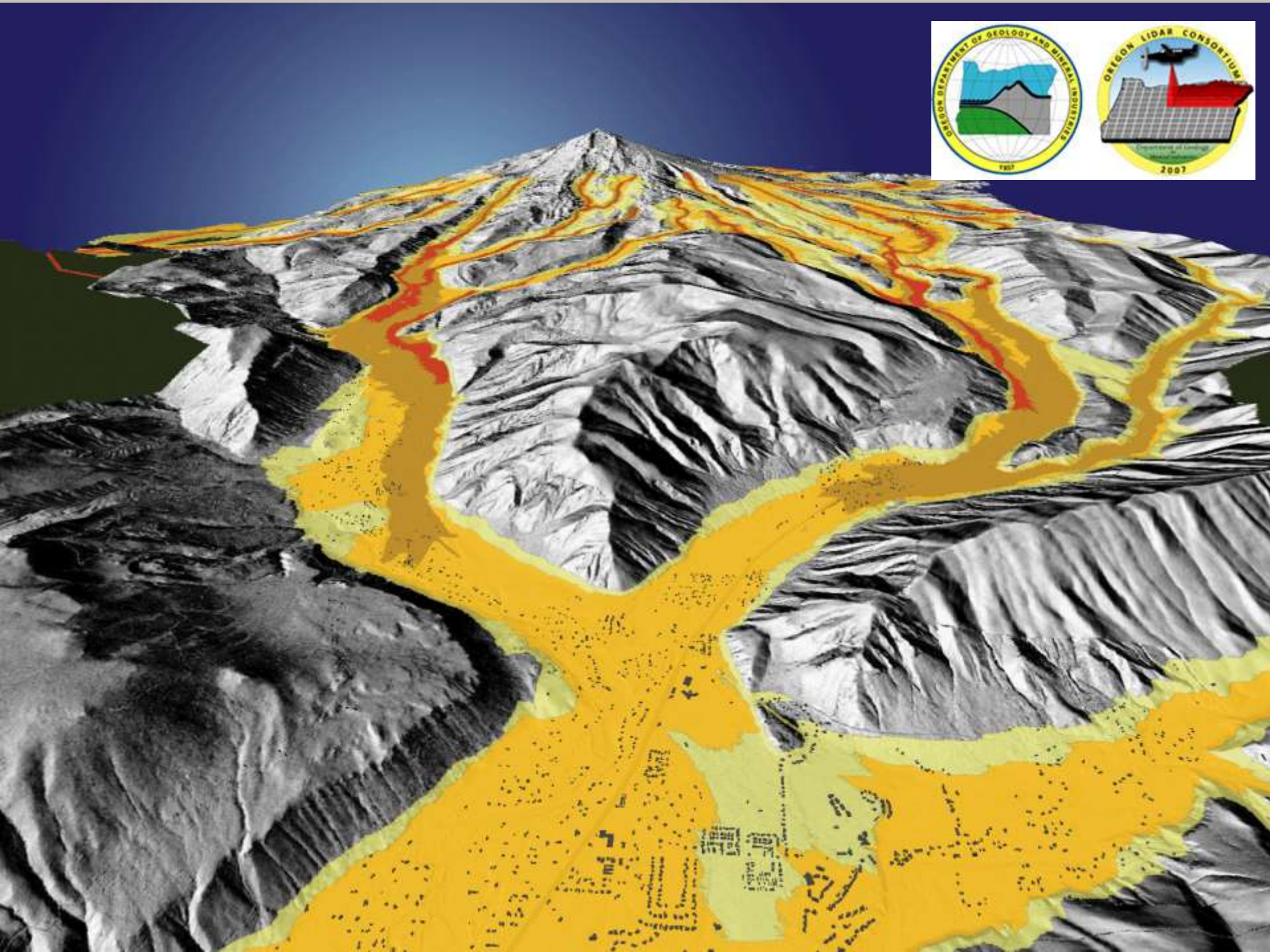


Figure by Keith Williams, Oregon State University

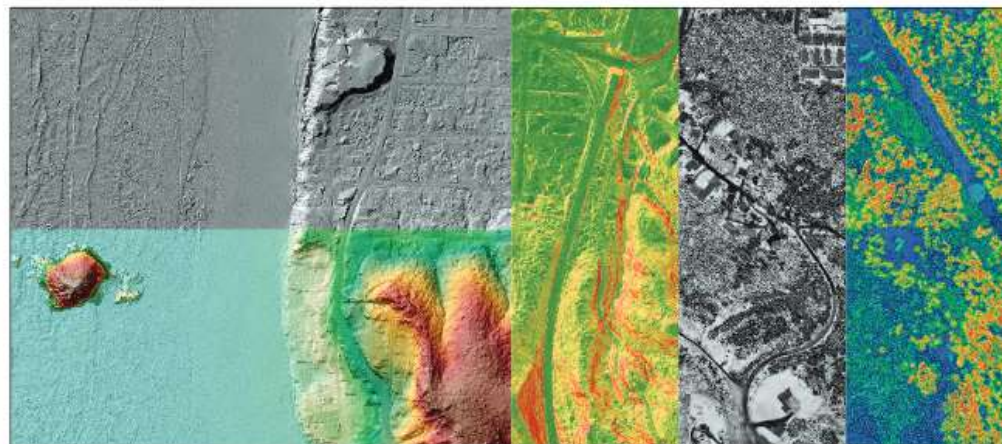
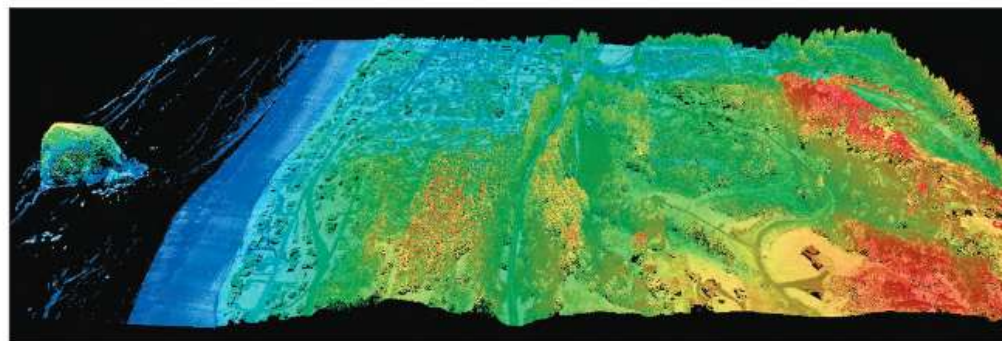
DATA COURTESY OF WATERSHED SCIENCES AND DOGAMI







The 3D Elevation Program Initiative—A Call for Action

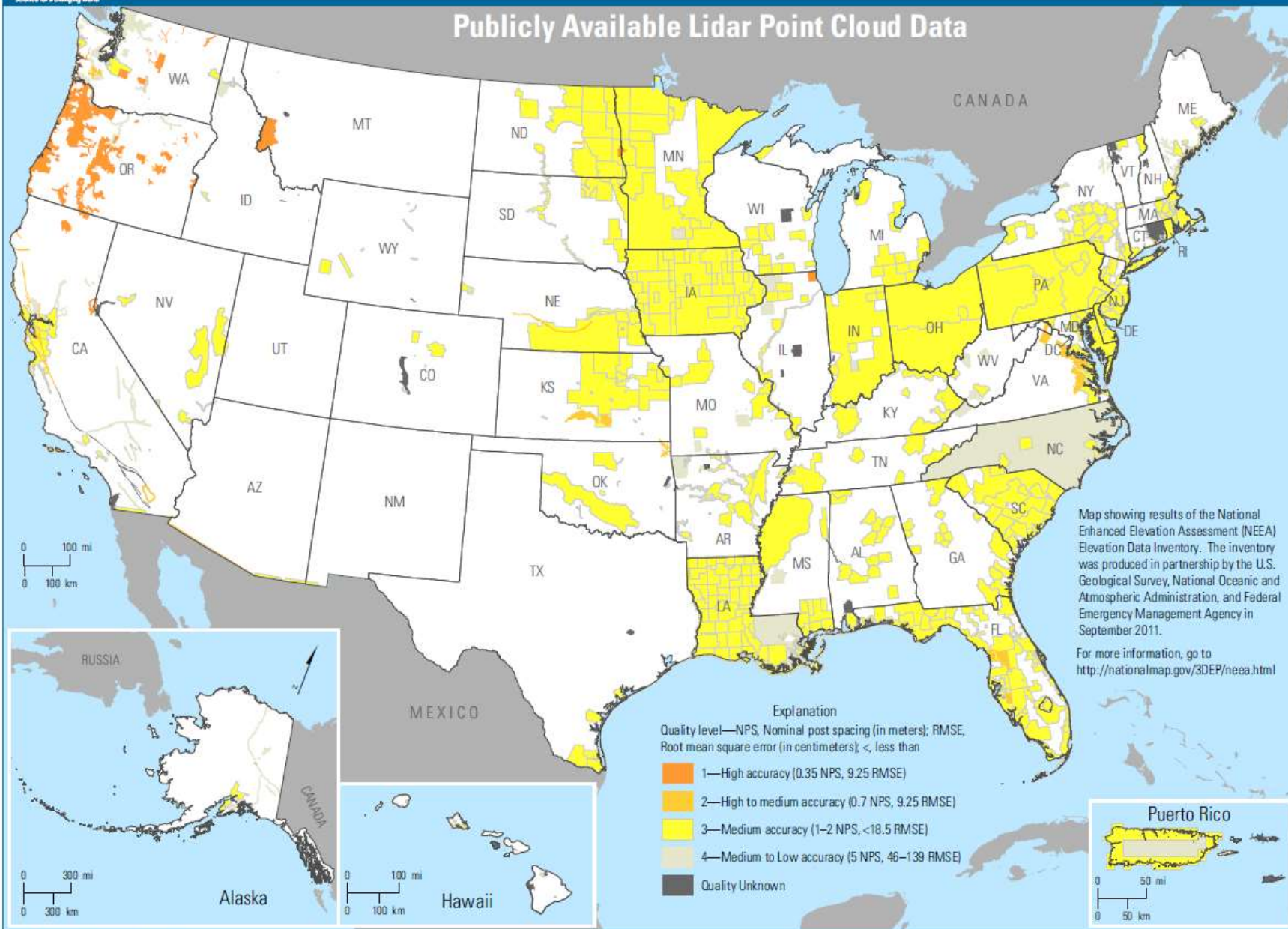


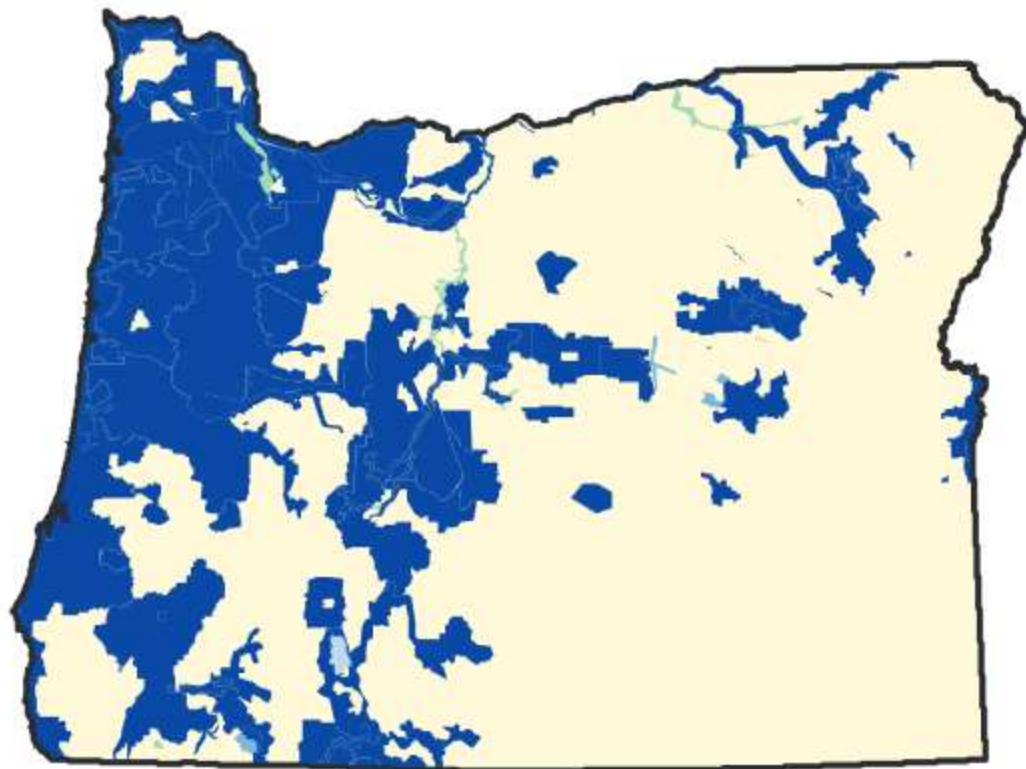
Sugarbaker, L.J., Constance, E.W., Heidemann, H.K., Jason, A.L., Lukas, Vicki, Saghy, D.L., and Stoker, J.M., 2014, The 3D Elevation Program initiative—A call for action: U.S. Geological Survey Circular 1399, 35 p., <http://dx.doi.org/10.3133/cir1399>

3DEP highlights

- >\$690 million annually in new benefits to private sector
- Estimated 5:1 return on investment
- Save lives
- Help economy
- Improve environment
- Collaboration within government
- Prepared for natural disasters (floods, landslides, earthquakes, etc.)
- Multiple agencies\disciplines benefit





Publicly Available Lidar Point Cloud Data





0 50 Miles
0 70 Kilometers

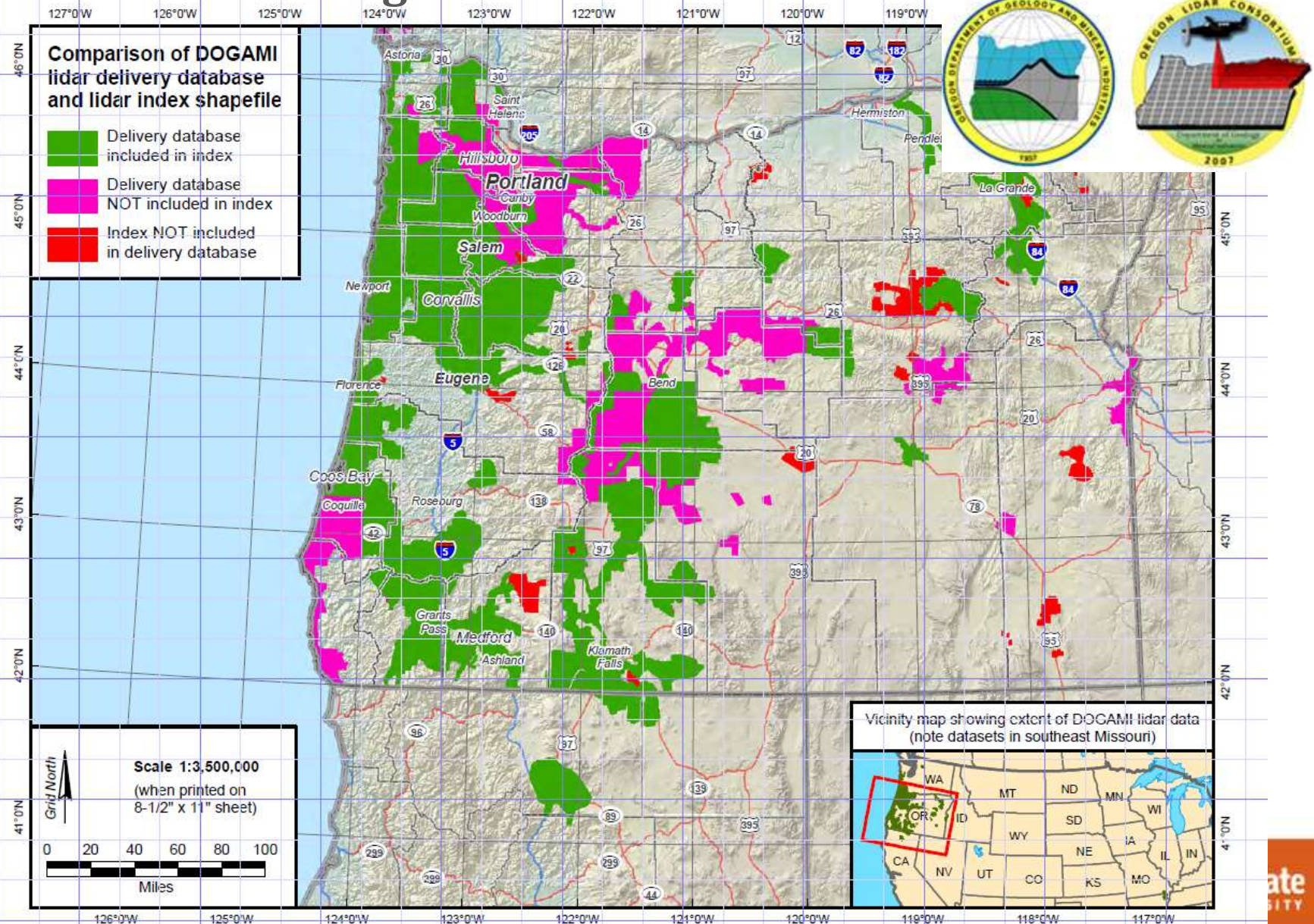
EXPLANATION

-  **Quality level 1
lidar data**
-  **Quality level 2
lidar data**
-  **Quality level 3
lidar data**
-  **Quality level 4
lidar data**
-  **No publicly available
lidar data**

Results of 3DEP inventory

- Lidar data have been collected over 28 percent of the conterminous United States and Hawaii.
- Enhanced elevation data (primarily ifsar data) have been collected over approximately 15 percent of Alaska.
- Elevation data was collected at an average annual rate of 4 to 5 percent from 2009-2011.
- The level of overlapping coverage is less than 10 percent.
- The quality of the data varies from project to project.

Oregon LIDAR Consortium



3D laser
scanner
w/ integrated
camera

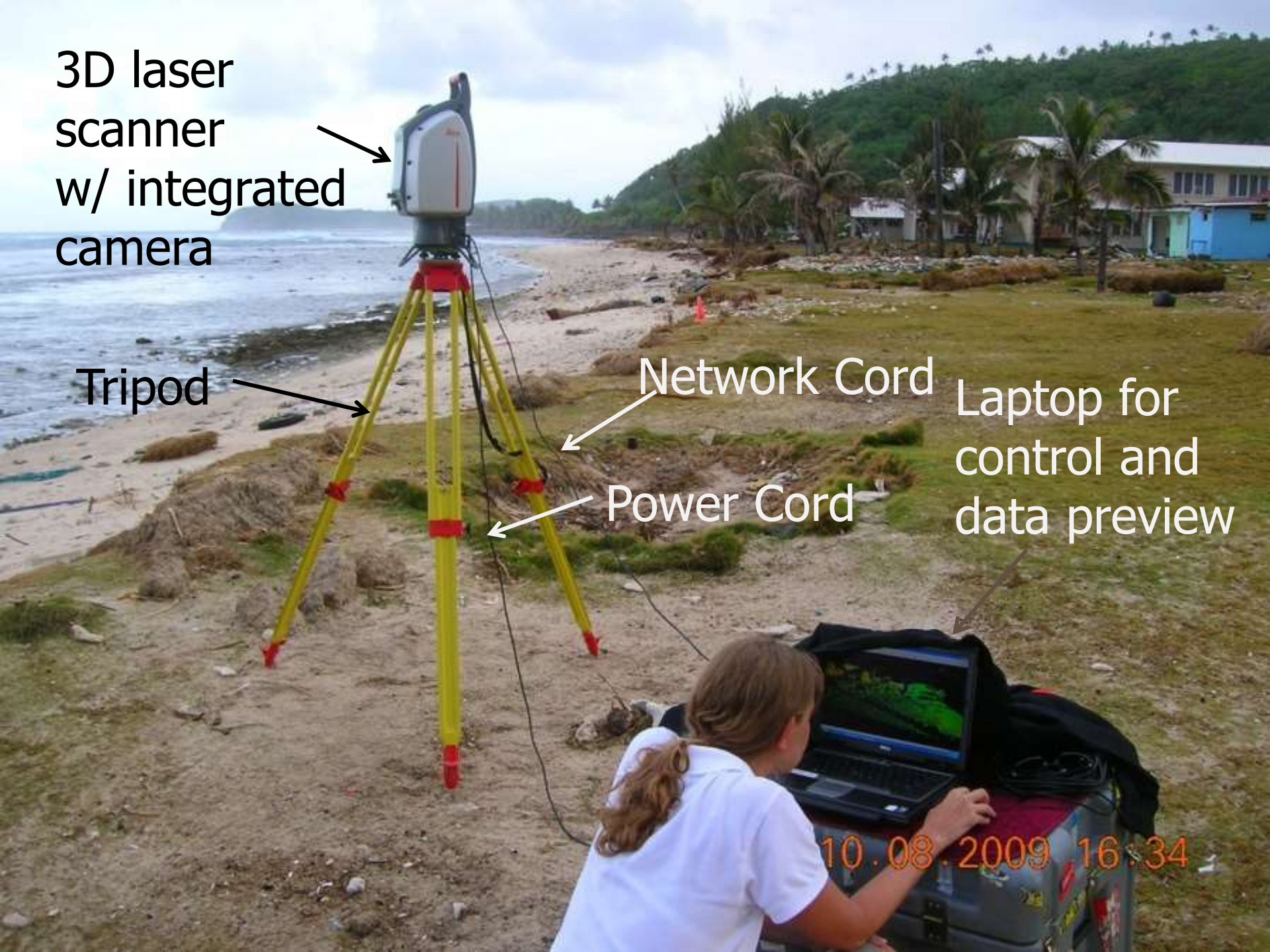
Tripod

Network Cord

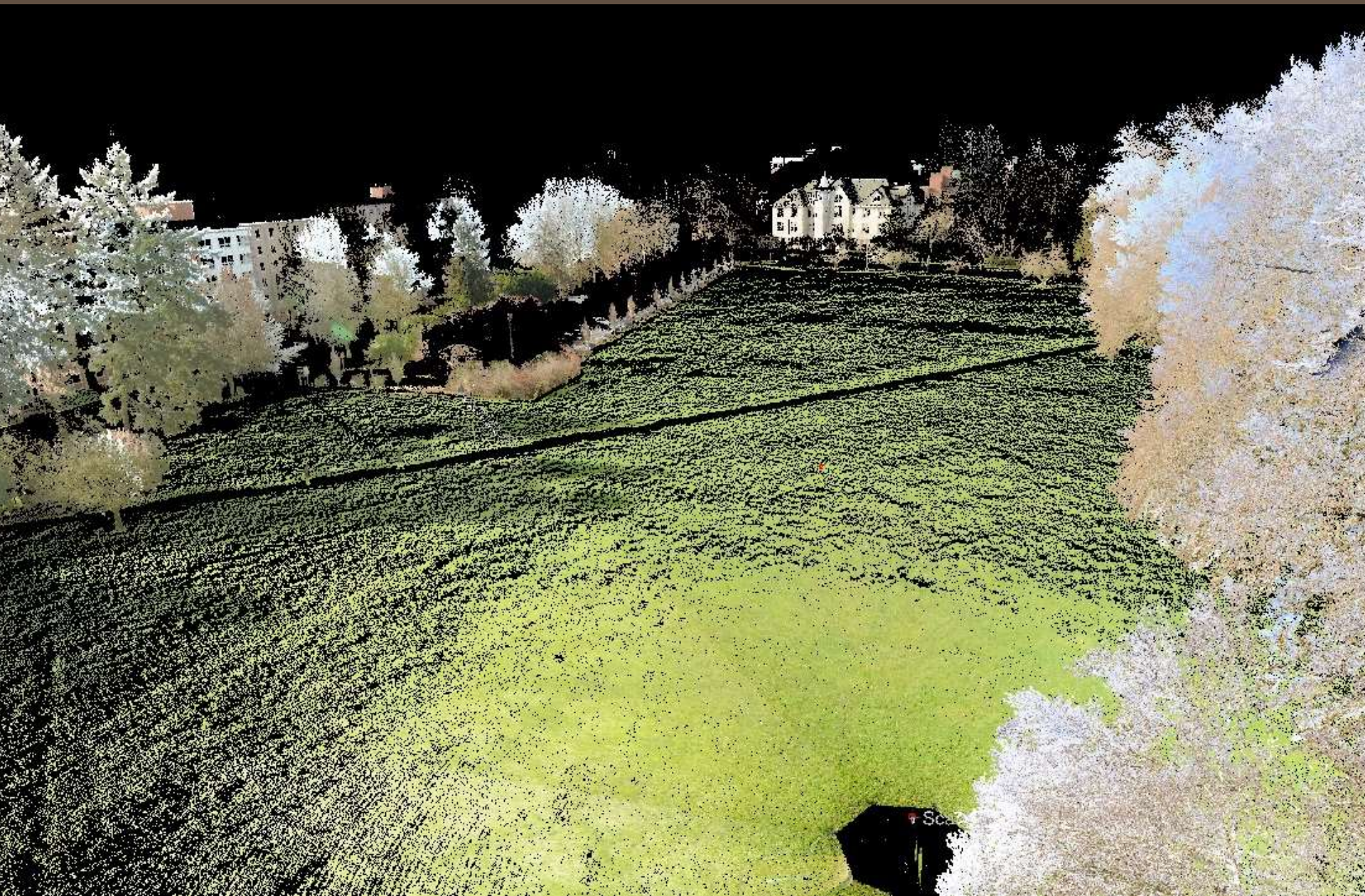
Power Cord

Laptop for
control and
data preview

10.08.2009 16:34









RTK GPS Receiver

3D Laser
Scanner

RTK GPS
Controller

Cell Phone

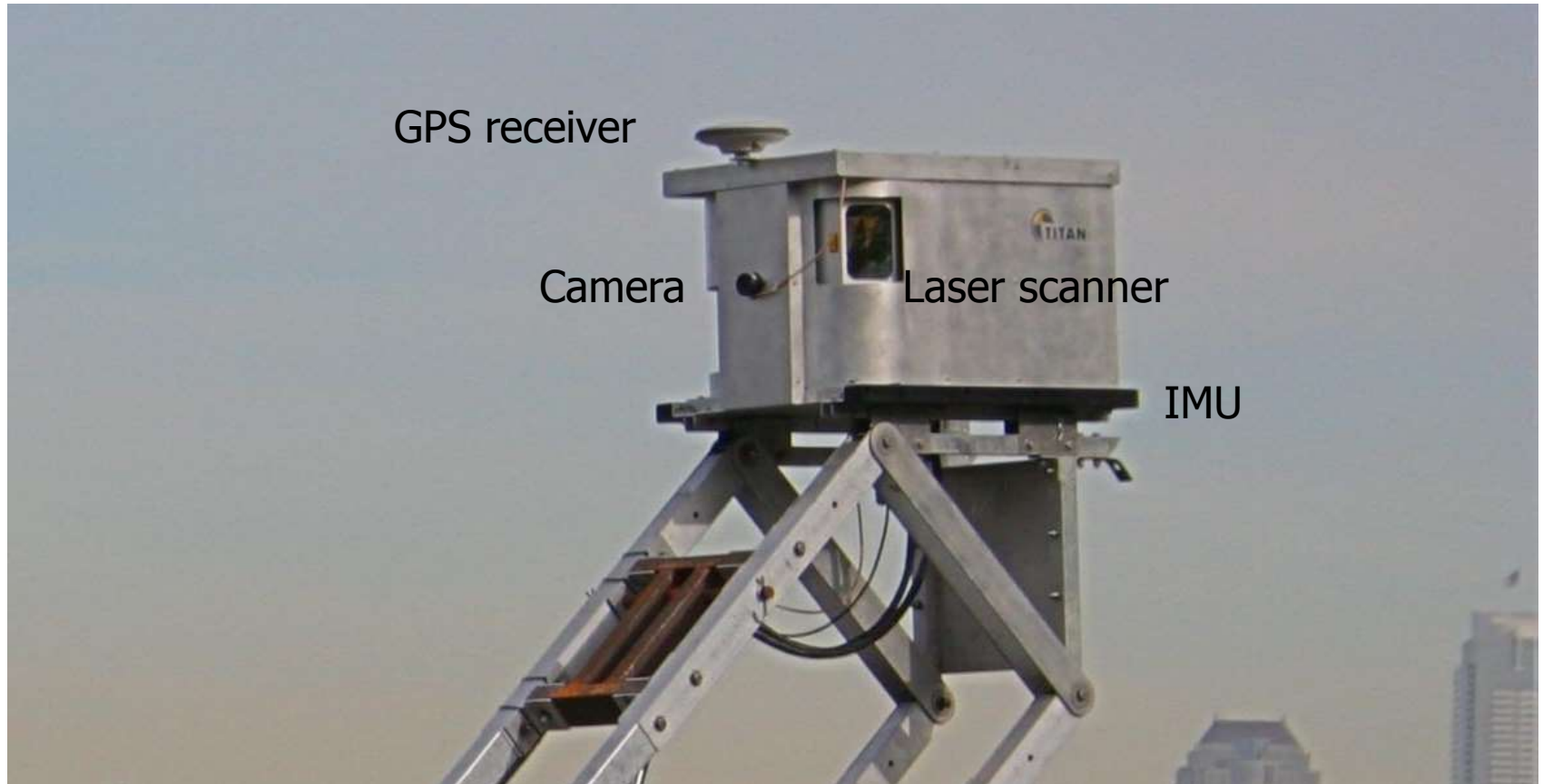
Laptop
Controller

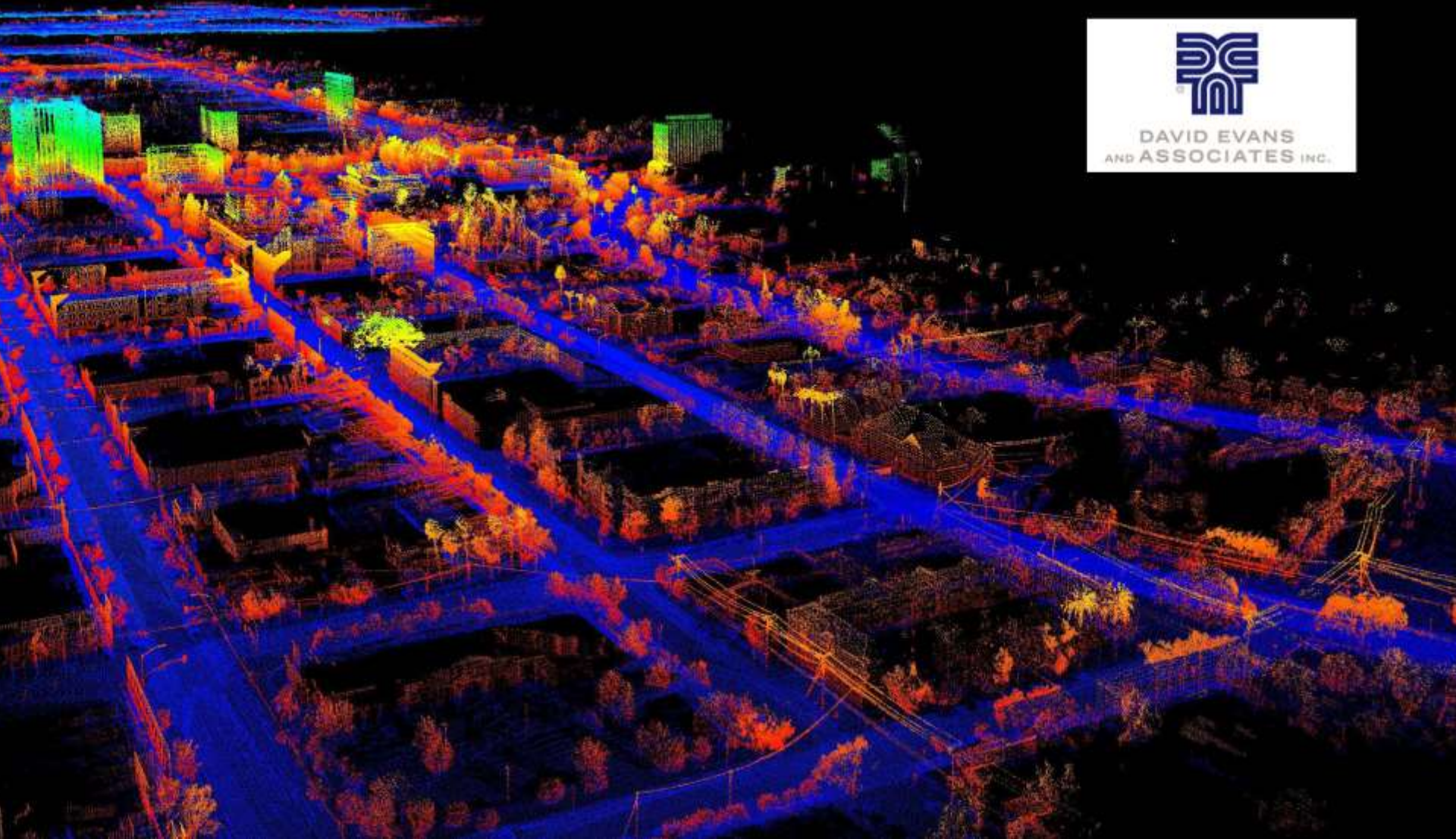
Mobile Laser scan system

GPS receiver Laser scanner
Camera

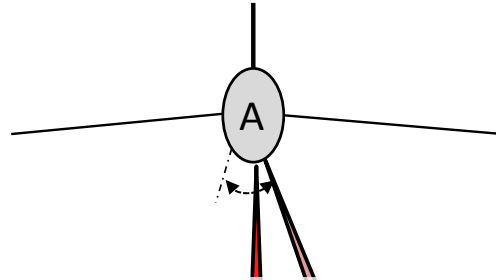


Components





DAVID EVANS
AND ASSOCIATES INC.

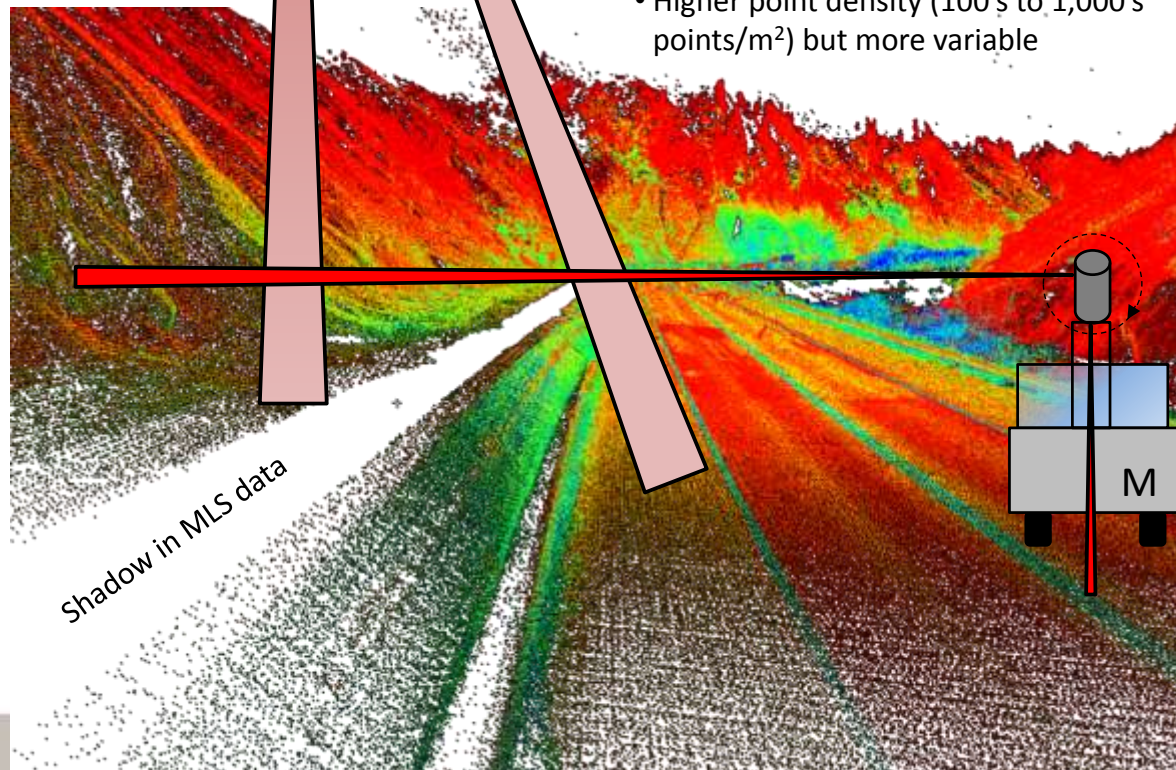


Airborne LIDAR

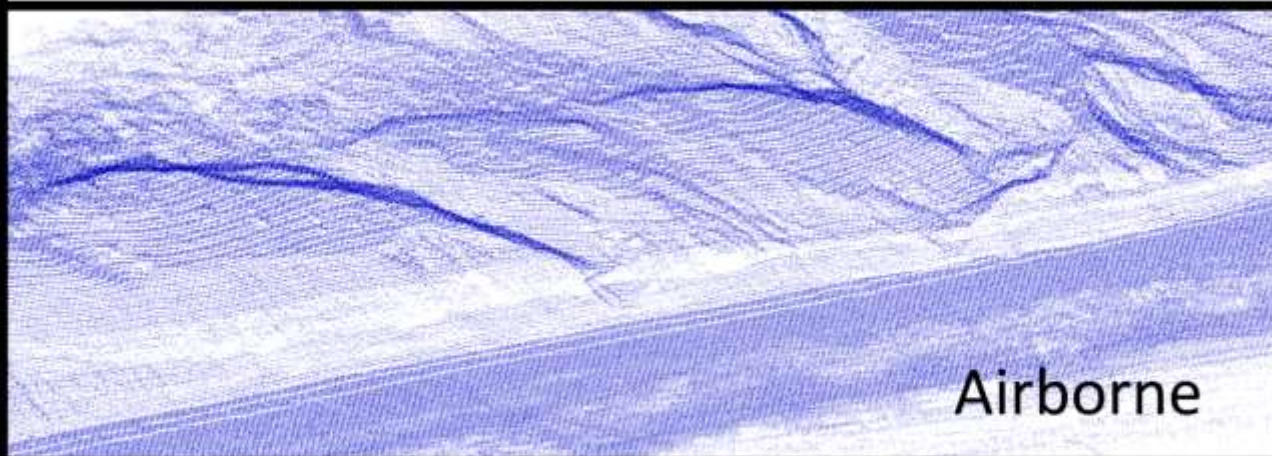
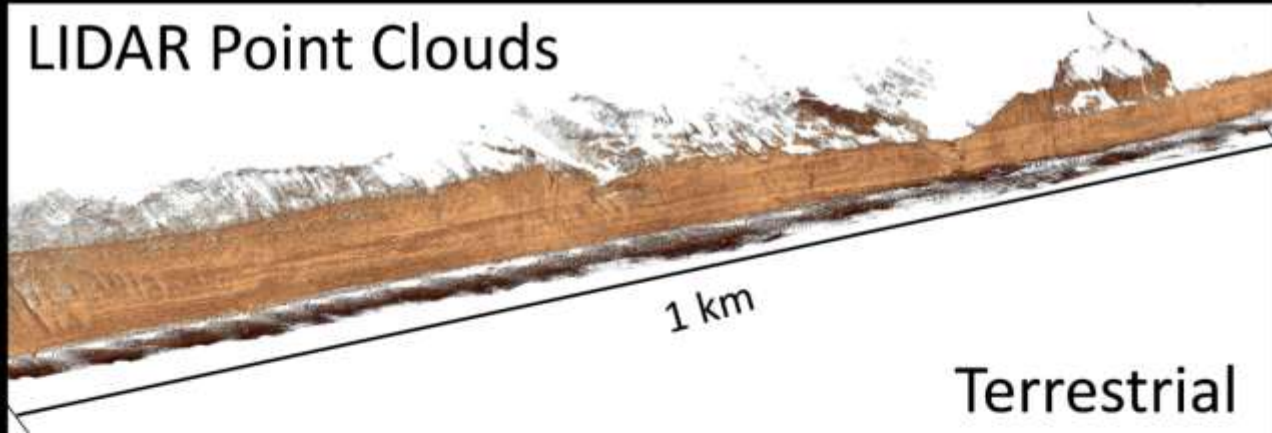
- Direct view of pavement & cliff tops
- Poor (oblique) view of vertical faces and cannot capture overhangs
- Faster coverage
- Larger footprint ($>0.5\text{m}$)
- Laser travels much farther
- Not limited to area visible from roadway
- Lower point density (1-80 points/ m^2)

Mobile LIDAR

- Good view of pavement
- Direct view of vertical faces
- Cannot capture cliff tops
- Slower coverage
- Smaller footprint (1-3 cm, typical)
- Closer to ground\objects
- Limited to objects close and visible from the roadway ($<100\text{m}$, typical)
- Higher point density (100's to 1,000's points/ m^2) but more variable



LIDAR Point Clouds



MLS Workflow

Level of LIDAR Expertise

- Expert
- - - Moderate experience
- - - Some experience
- - - Novice

Planning

- Quality Management Plan
- Determine sections of interest
- Coordinate with divisions\ agencies
- Weather\ Environment Conditions
- Determine which sensors are needed
- GNSS PDOP prediction
- Topography\land cover\water
- Develop drive path

Preliminary Site Surveys

- Determine obstructions
- Traffic peaks
- Determine what can be covered by MLS

Packaging and Delivery

- Develop reports
- Zip Data
- Evaluate strategy efficiency for future missions
- Archive and backup data

Docs

Data Acquisition

- Verify system calibration
- Set and acquire control and validation points
- Drive and monitor the mission
- Scan Data
- GNSS\IMU
- Imagery
- Other sensors

Raw

Img

Geo referencing

- Combine LIDAR, GNSS, and IMU
- Geometric Correction
- Local Transformation
- Validate accuracy\resolution\ completeness
- Tile Data

Reg

Post Processing

- Clean and filter data
- Classify data
- Surface (model) data
- Extract Features\line work
- QC models and features

Mod

Clas

Computations\Analysis

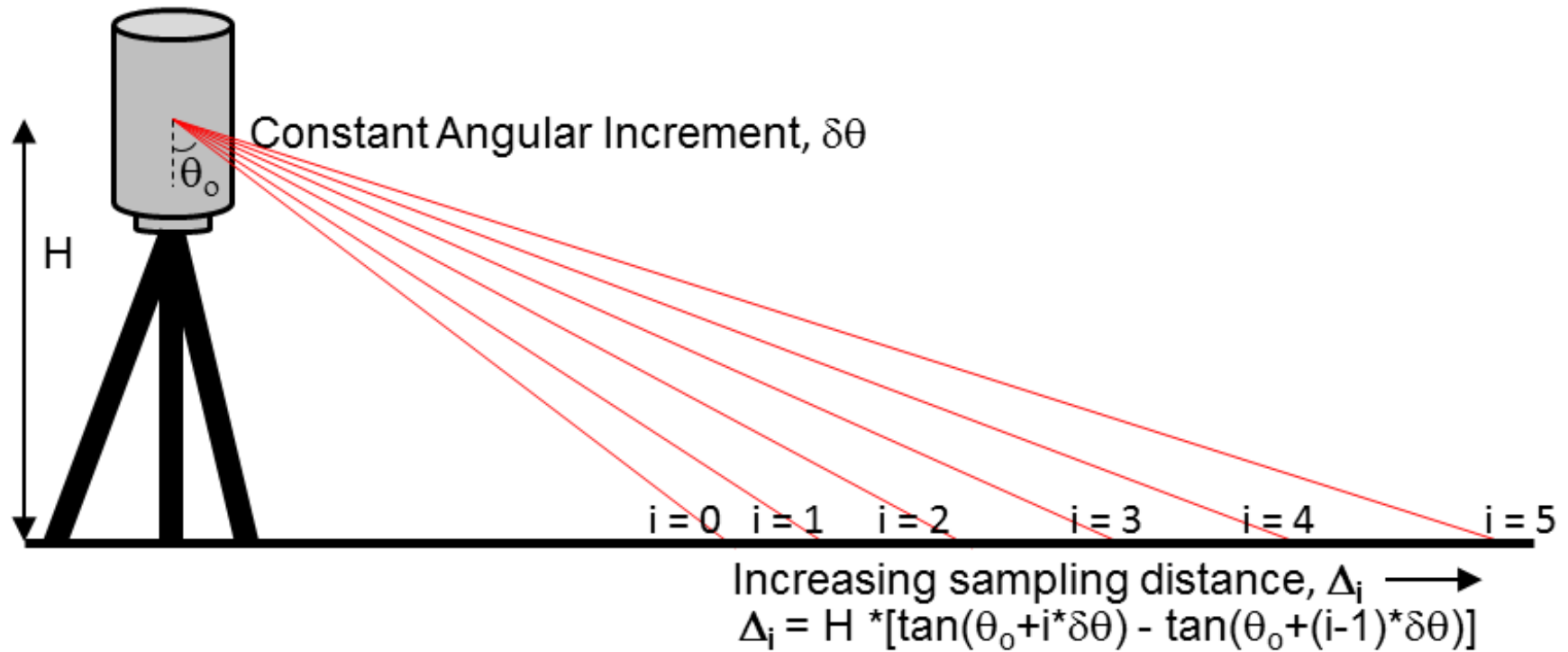
- Create DEM derivatives
- Derive point density map
- Detect change\deformation
- Cut\Fill estimation
- QC analysis results

Calcs

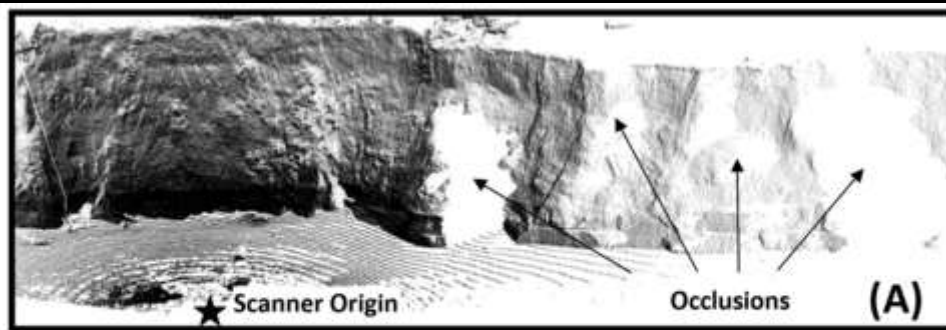
Fails QC

Fails QC

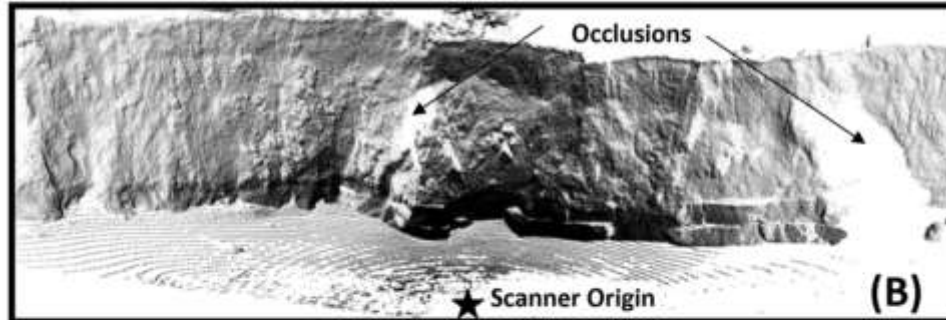
Scanning geometry



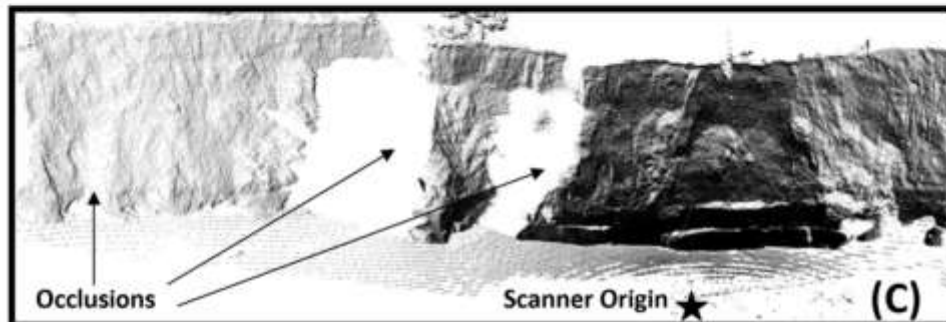
Scan A



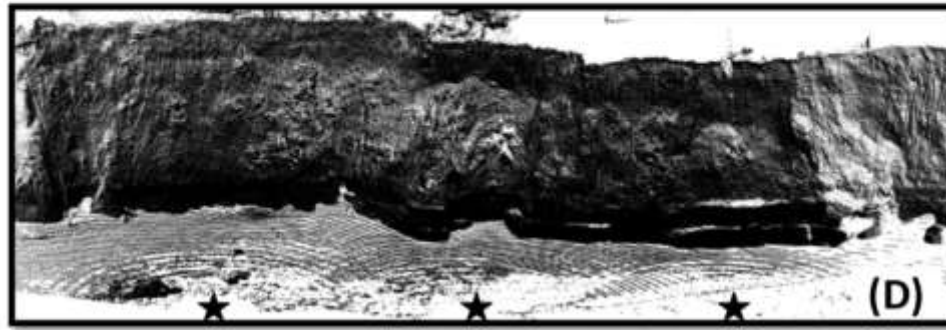
B



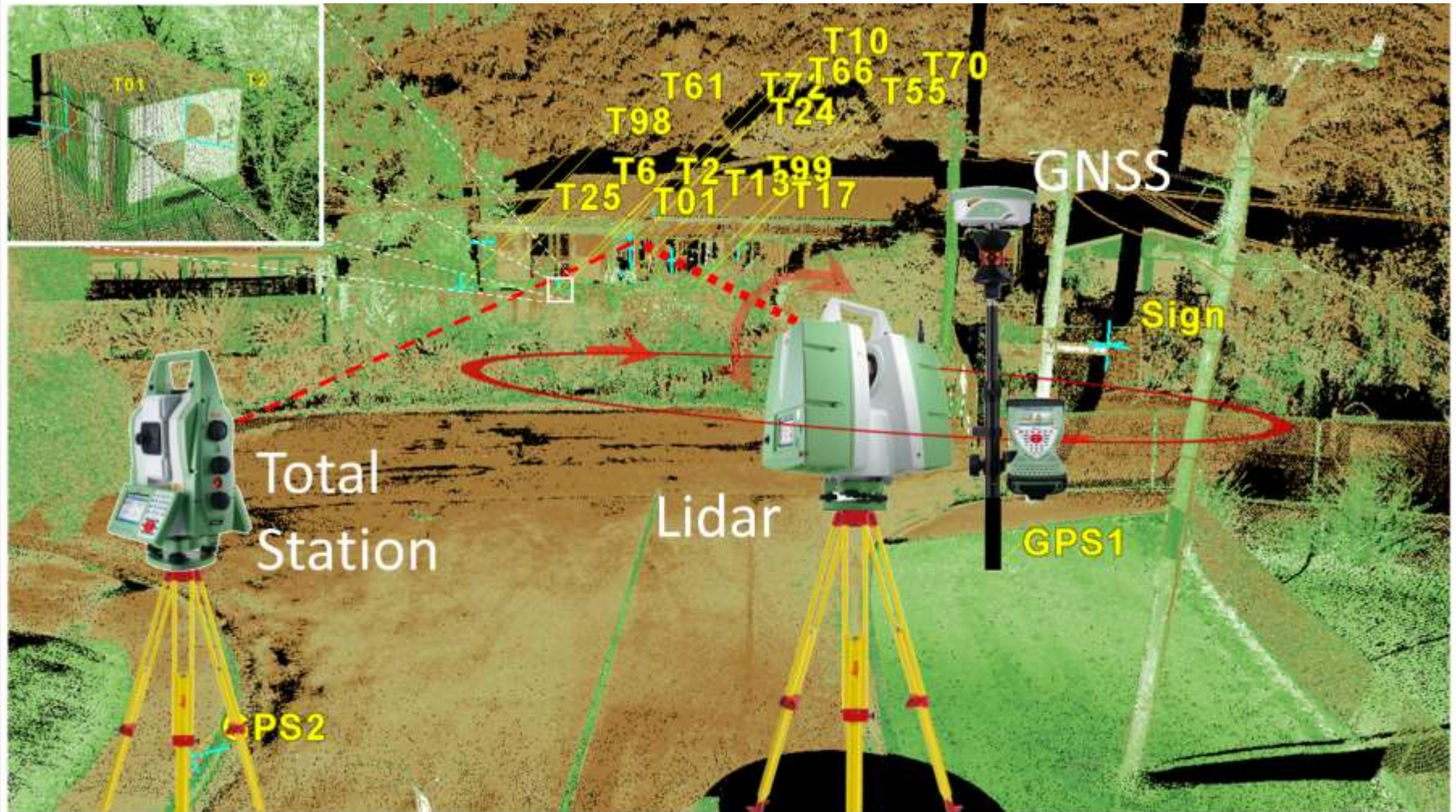
C



A+B+C



Integration of Geomatics Technologies



Mathematically defined, Geometric Primitives

points

lines and line segments

planes

circles and ellipses

triangles and other polygons

spline curves

spheres

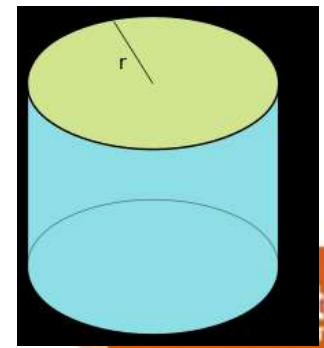
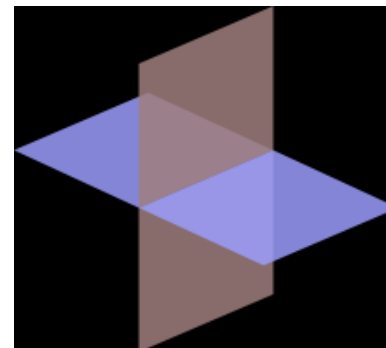
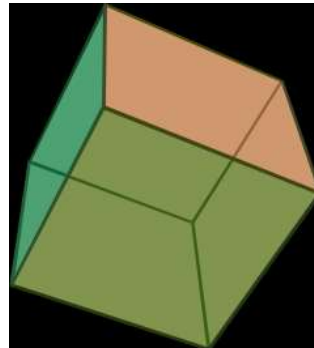
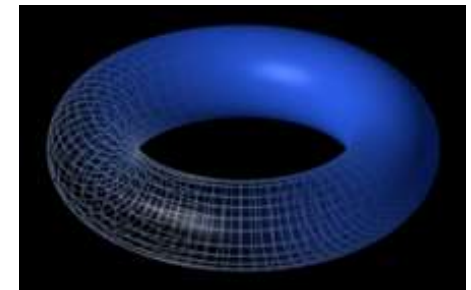
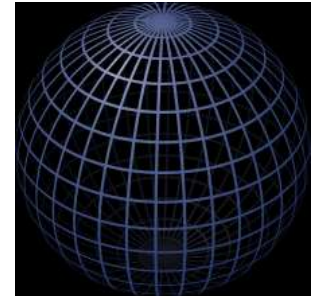
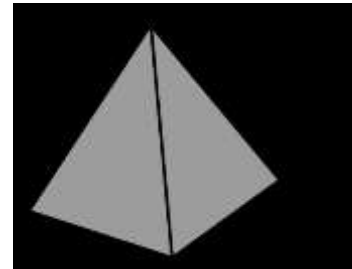
cubes or boxes

toroids

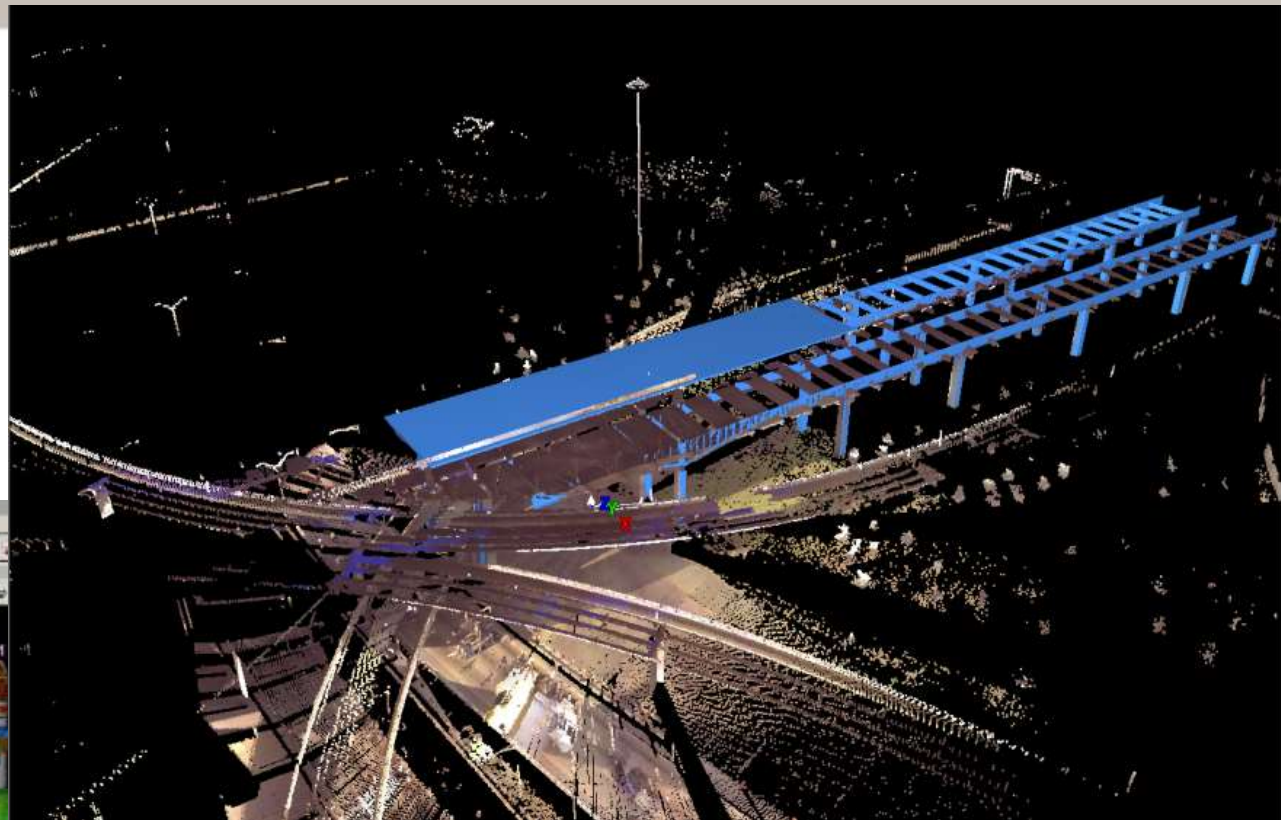
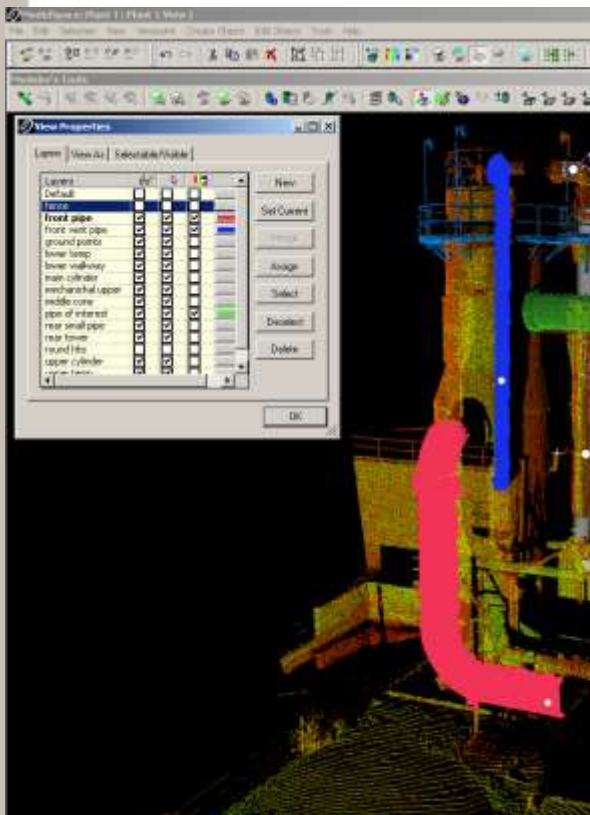
cylinders

pyramids

teapot



Modeling in Leica Cyclone

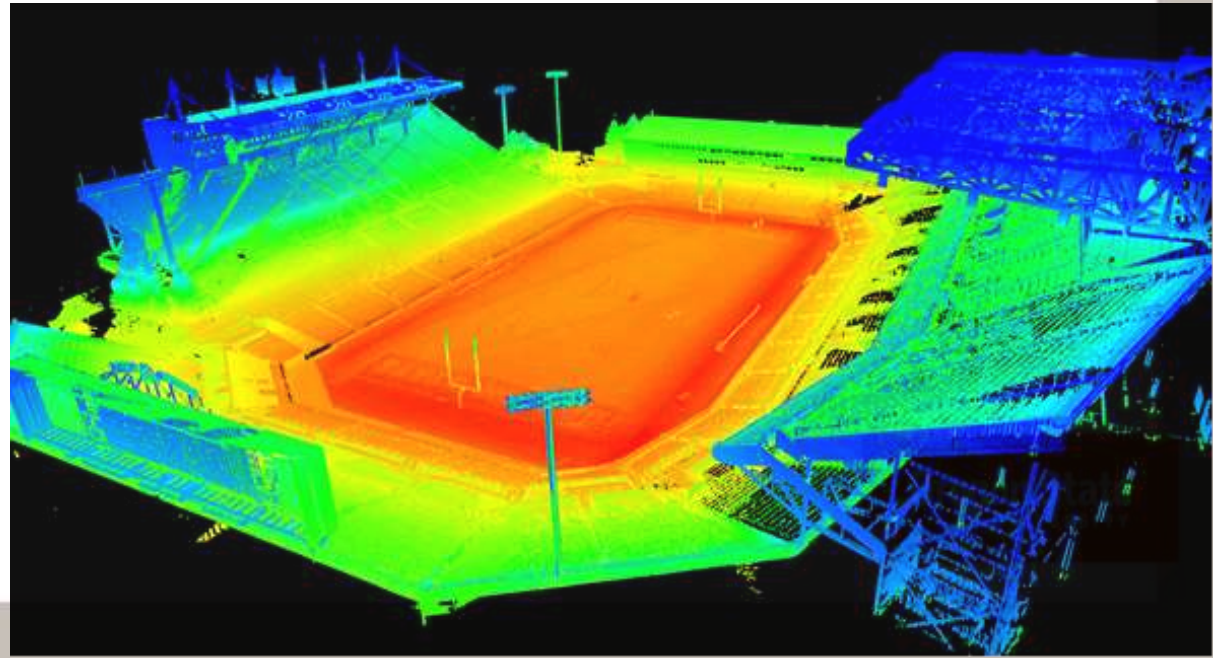


By:
Logan Allendar
Torgor Torgerson

Oregon State
UNIVERSITY

Example Applications

- Transportation
- Coastal Erosion
- Landslide Assessment
- Earthquake and Tsunami damage assessment
- Wireless signal mapping
- Cultural Heritage
- Laboratory Testing



NCHRP 15-44 (Report #748) Guidelines for the use of mobile lidar in transportation applications



MPN Components

Persi Consulting

Martha Hales Design

Alisa Bolander Consulting



DAVID EVANS
AND ASSOCIATES INC.

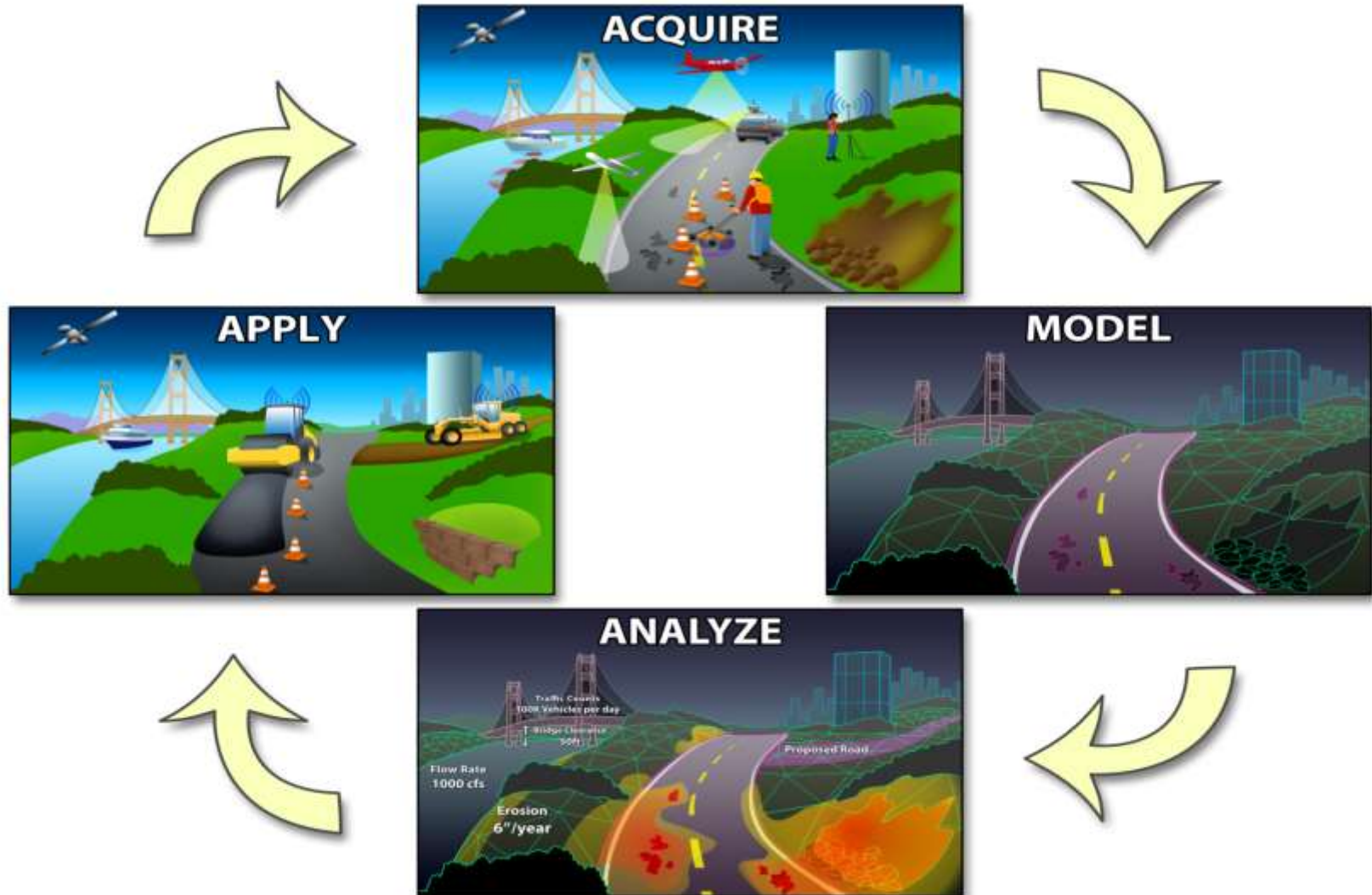
Oregon State
UNIVERSITY



Graduate Students: Keith Williams, Matt O'Banion

Oregon State
UNIVERSITY

Transportation Asset Lifecycle





LEARN

<http://learnmobilelidar.com>

GUIDELINES FOR THE USE OF MOBILE LIDAR IN TRANSPORTATION

Welcome to the online resource for the NCHRP 15-44 Guidelines for the use of Mobile LIDAR in Transportation Applications. Mobile LIDAR is one of several new 3D technologies that offer the promise of transforming the way in which transportation agencies plan, design, construct and maintain their highway networks. This website is designed to facilitate the interactive learning of the guidelines document and serve as a central hub for discussion and transmission of knowledge amongst the Mobile LIDAR community.

Getting Started



Review key overview references for Mobile LIDAR.

E-Learning Modules



Learn about mobile LIDAR technology and how to manage it.

Mobile LIDAR Forum



Join others in the discussion of mobile LIDAR.

News Feed

[International LiDAR Mapping Forum Launches 2014 Program - GISuser.com \(press release\)](#)

Literature Database

Welcome to the Literature Database. This database includes all references cited in NCHRP Report 748 as well as other references relevant to mobile LIDAR and geomatics. Most references can be viewed by clicking on the title of the reference. If you know of relevant references which are not included or come across a broken link, please [Click Here](#) to let us know.



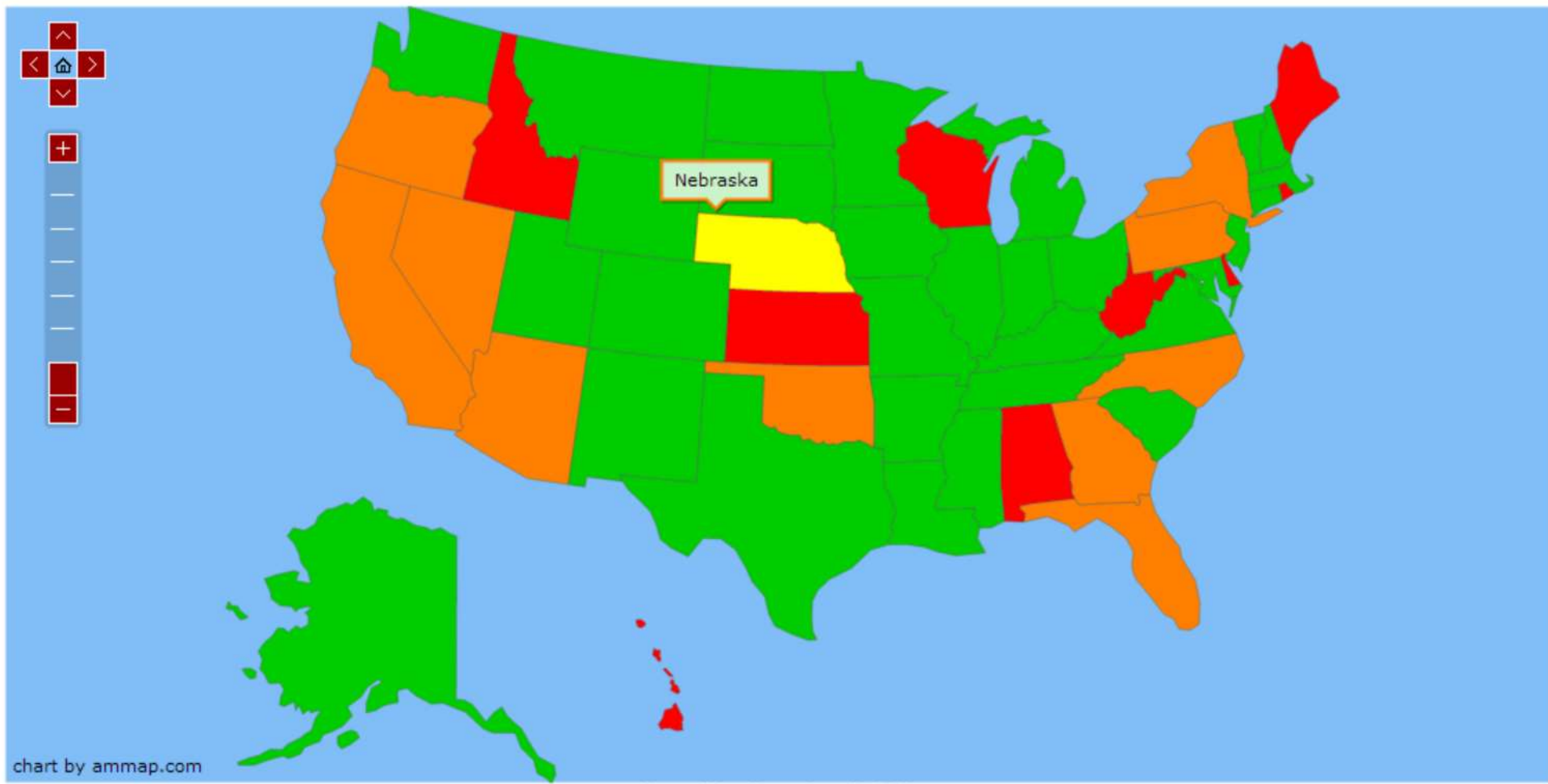
Search:

Title	Date	Author	Key Terms	Source
3DLM Helps Reduce Motorway Congestion	2011	3D laser mapping	Transportation, Traffic, Accident	News
Highway Safety Manual	2010	AASHTO	Transportation	Manual
Guidelines for Procurement of Commercial Geospatial Products (DRAFT)	2011	ASPRS	Geospatial, Mapping	Guidelines
ASPRS Guidelines: Vertical Accuracy Reporting for Lidar Data	2004	ASPRS Lidar Committee	Specifications, Standards	Guidelines
ASPRS LIDAR Guidelines: Horizontal Accuracy Reporting (DRAFT ver. 0.9)	2005	ASPRS Standards Committee	Specifications, Standards	Guidelines
LAS 1.4 Specification Approved by ASPRS Board	2011	ASPRS	File Format	Guidelines
LASer (LAS) Specification, Version 1.4-R11	2011	ASPRS Standards Committee	File Format	Guidelines
Lib E57: Software Tools for Managing E57 Files	2010	ASTM	File Format	Guidelines
Airborne laser scanning: basic relations and formulas	1999	Baltsavias, E.P.	ALS, scan patterns	Journal
Geometric validation of a ground-based mobile	2008	Barber, D., J. Mills, S. Smith-	Accuracy, Terrestrial, Mobile Mapping, Validation	Journal

photogrammetry, and GPS. If you know of relevant specifications which are not available or need to be updated please [Click Here](#) to let us know.

Select a State:

Last Updated: 04/04/1



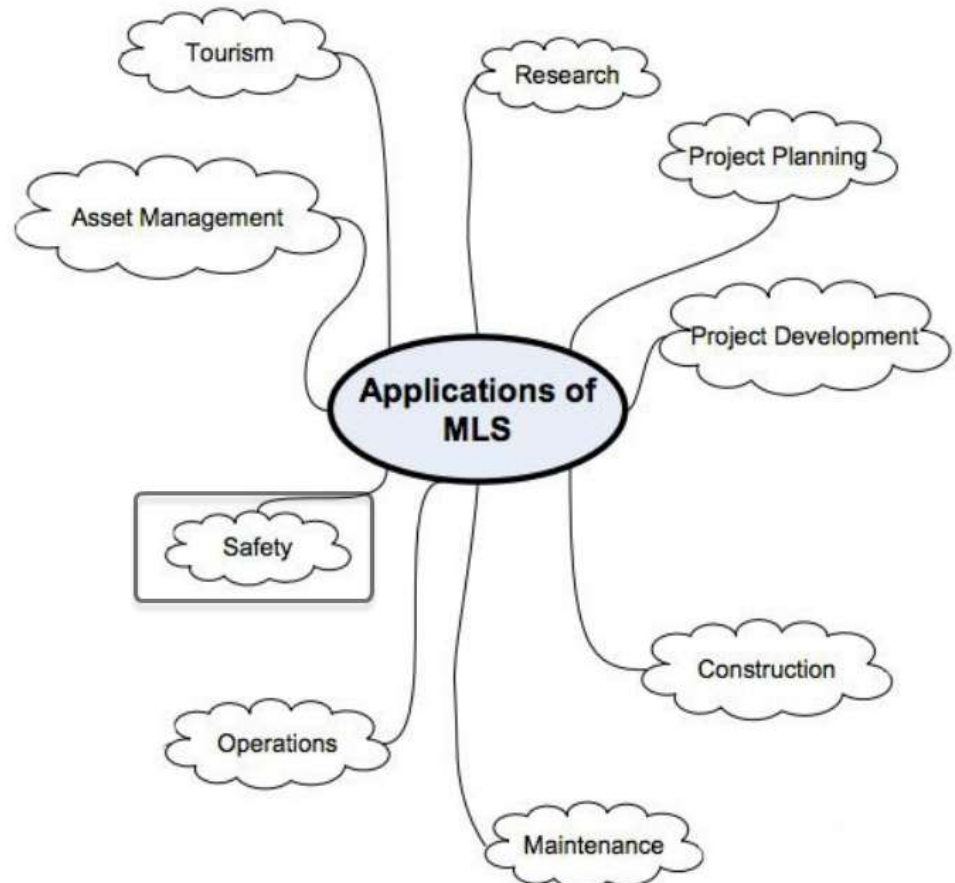
Specification Availiily

- Surveying
- LIDAR
- None



Potential applications

Click on each of the applications shown at right to learn more about how Mobile LIDAR may be used in that context.



Potential applications

Tourism applications

Tourism is an emerging mobile LIDAR application. As tools to visualize point clouds from LIDAR systems become available, mobile LIDAR can provide a new generation of 3D, digital maps for navigation and exploration.

A 2009 report describes the efficiency gains possible with the acquisition of mobile LIDAR in the historic peninsula of Istanbul.

- Only 80 ha of the required 1500 ha were completed using static scanning in 6 months
- The remaining 1420 ha were completed in 3 months using mobile LIDAR.



Stop-and-go LIDAR point cloud of Balboa Park, San Diego, CA

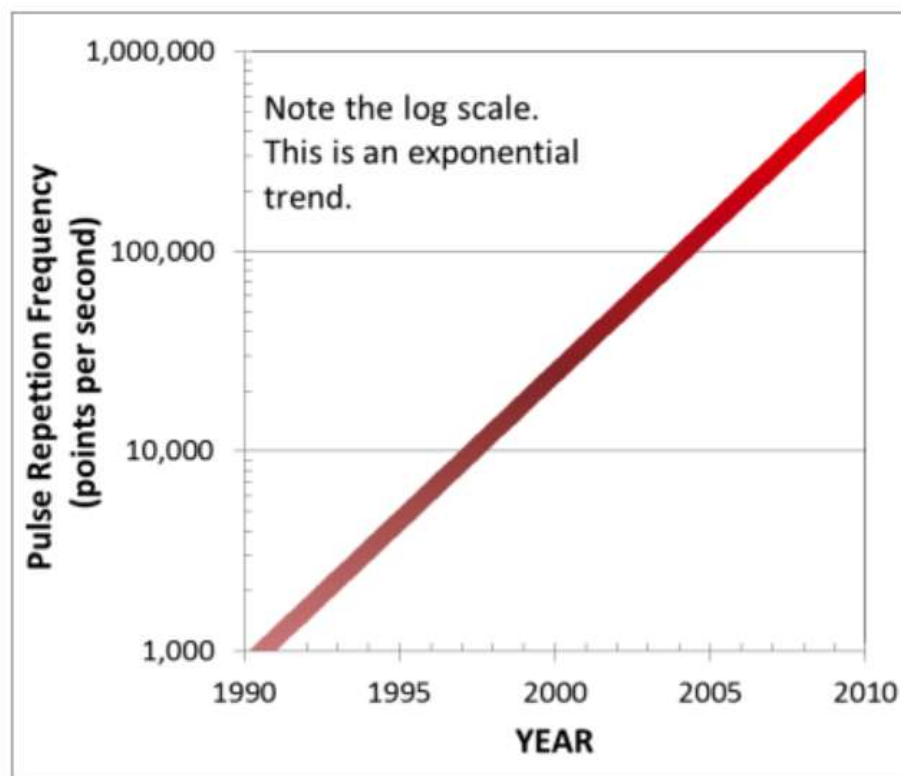
Guidelines, A.6.8.

Return

LIDAR point sampling

Percent complete: 82%

Over the 20 year period from 1990 to 2010, the point sampling capability of laser scanners has increased from 1,000 points/second to over 1 million. This impressive improvement in the ability to collect data faster also results in increased challenges when it comes to managing that data.



< PREV

NEXT >

Knowledge check: How MLS technology works

Below is an image of an MLS system and with descriptions of the components. Drag each description to place it on top of the correct component.

Click **SUBMIT** to lock in your answer.

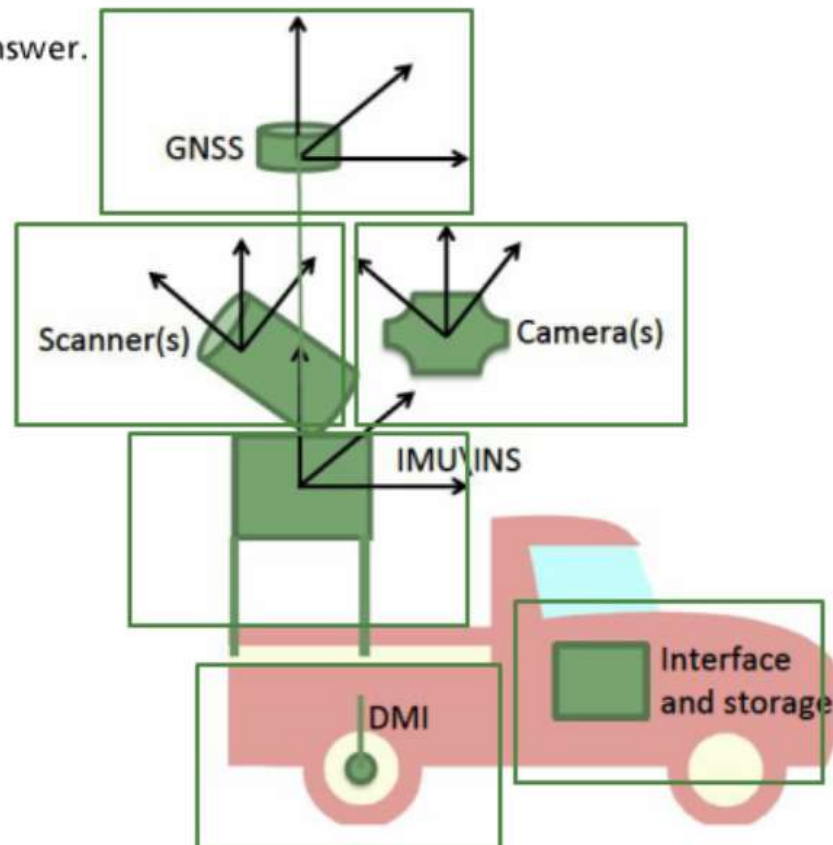
Provides additional detail that allows color to be added to point clouds

Provides time, position, and velocity measurements

Provides orientation and attitude information and position estimation

Fires pulses or continuous waves that determine the range to objects

Provides an estimate of distance traveled



< PREV

SUBMIT

Knowledge check: How MLS technology works

Below is an image of an MLS system and with descriptions of the components. Drag each description to place it on top of the correct component.

Click **SUBMIT** to lock in your answer.



Incorrect

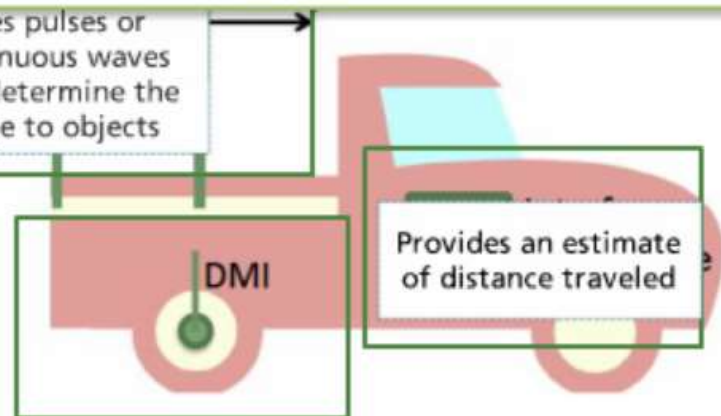
That's not quite right. Try again.

Try Again

Fires pulses or continuous waves that determine the range to objects

DMI

Provides an estimate of distance traveled



< PREV

SUBMIT

Knowledge check: How MLS technology works

Below is an image of an MLS system and with descriptions of the components. Drag each description to place it on top of the correct component.

Click SUBMIT to lock in your answer.

Correct

Well done! You labeled all of the components correctly.

Continue

Provides orientation and attitude information and position estimation

Provides an estimate of distance traveled

Interface and storage



< PREV

SUBMIT

Knowledge check: How MLS technology works

Below is an image of an MLS system and with descriptions of the components. Drag each description to place it on top of the correct component.

Click SUBMIT to lock in your answer.

Correct

Well done! You labeled all of the components correctly.

Continue

Provides orientation and attitude information and position estimation

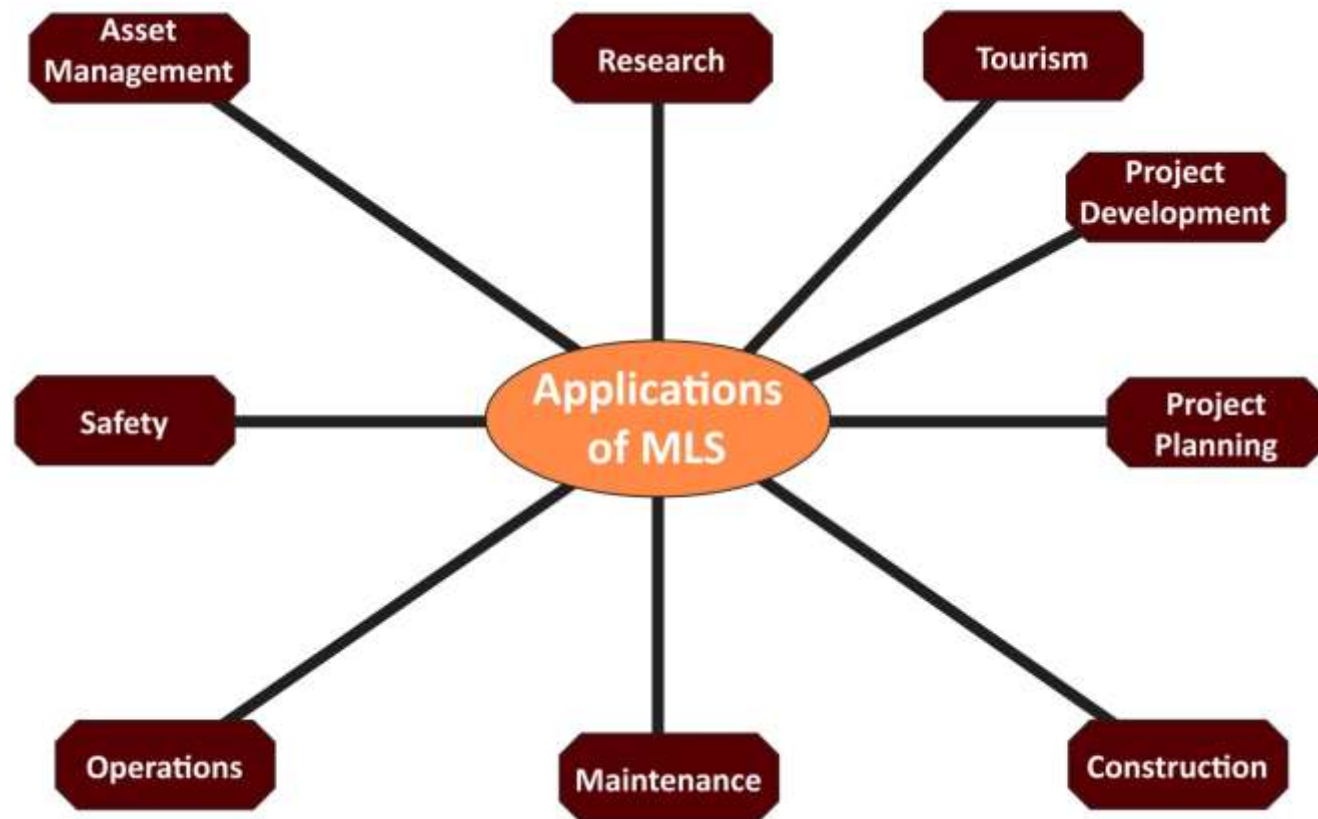
Provides an estimate of distance traveled

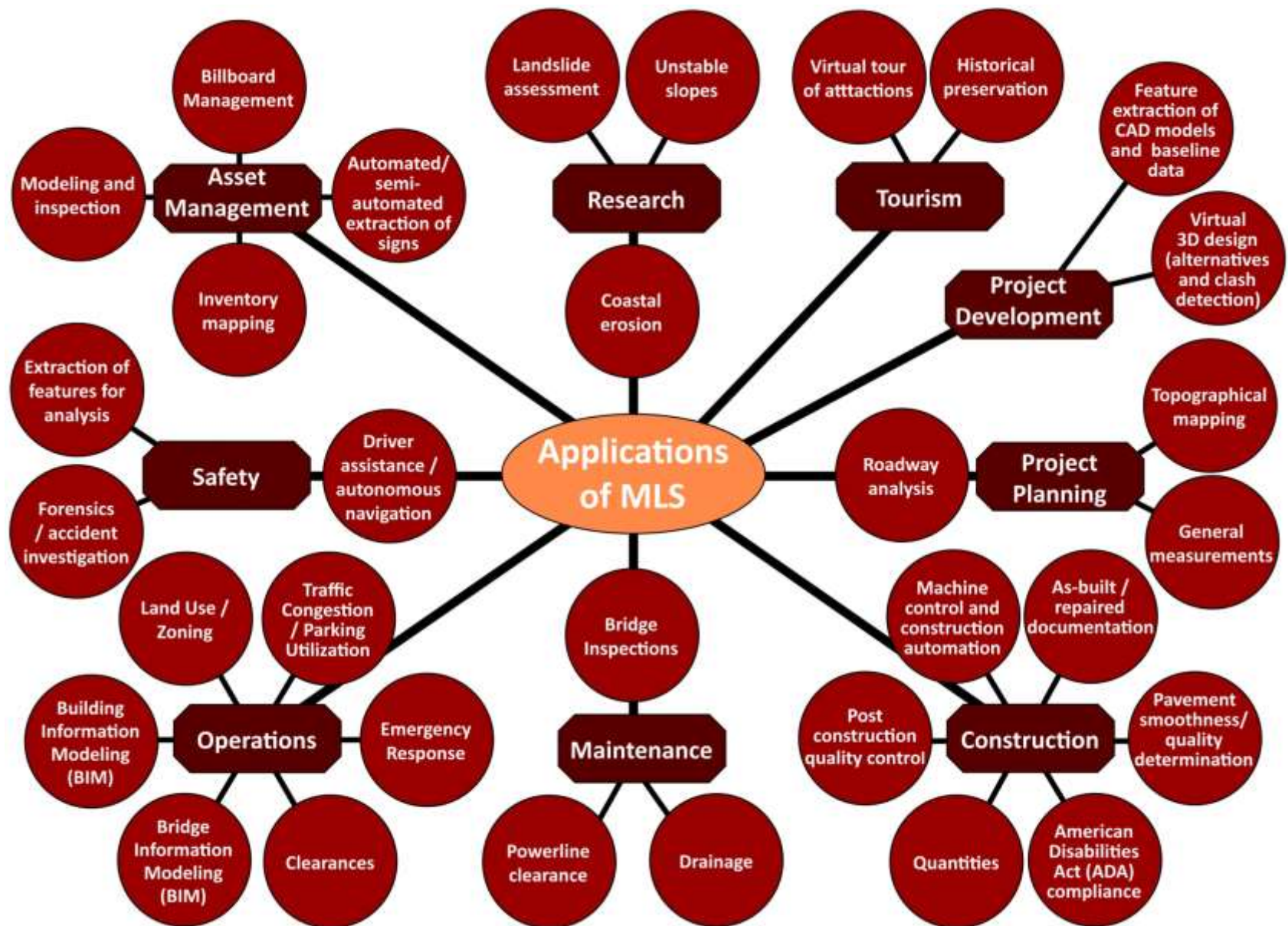
Interface and storage



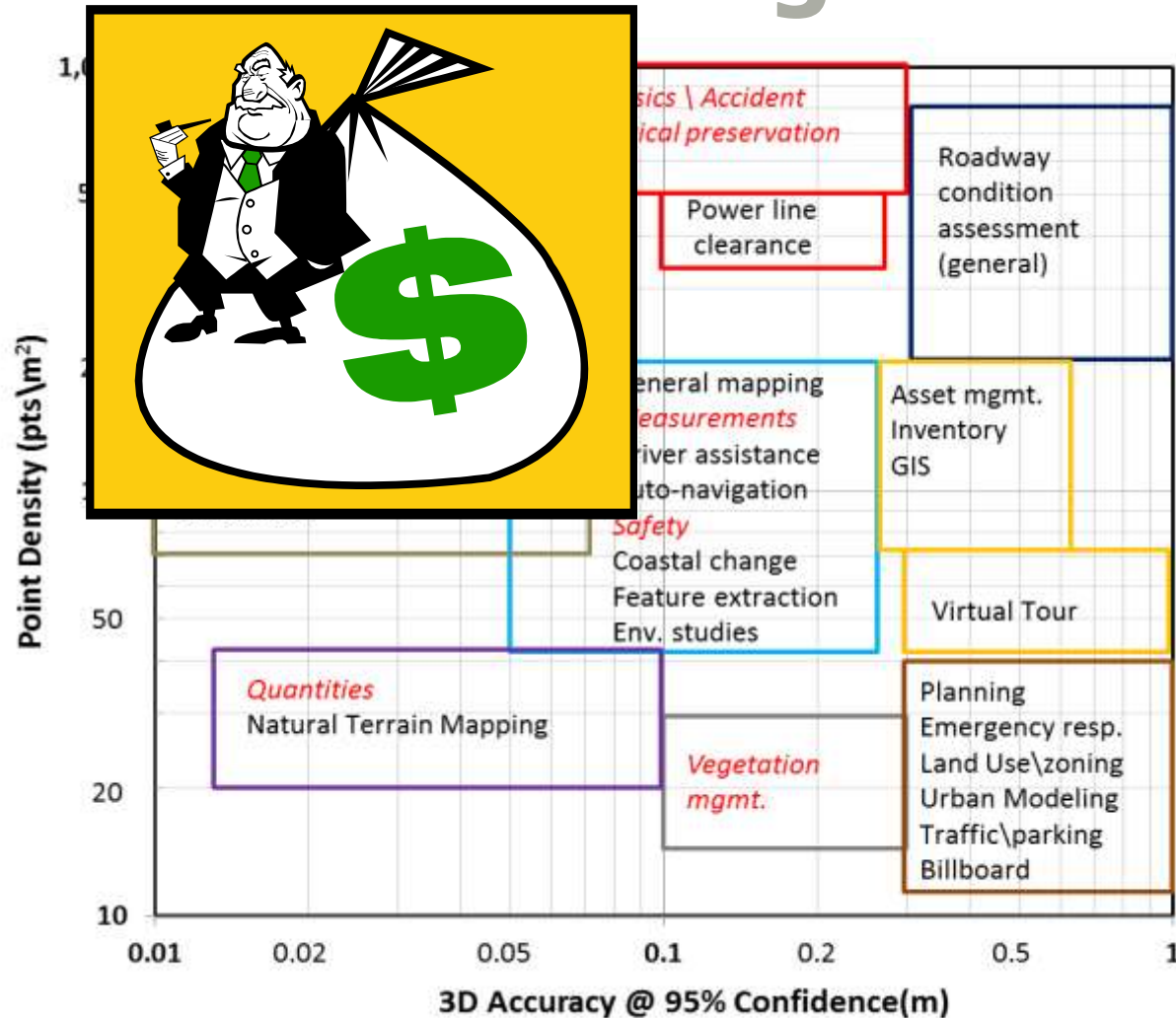
< PREV

SUBMIT



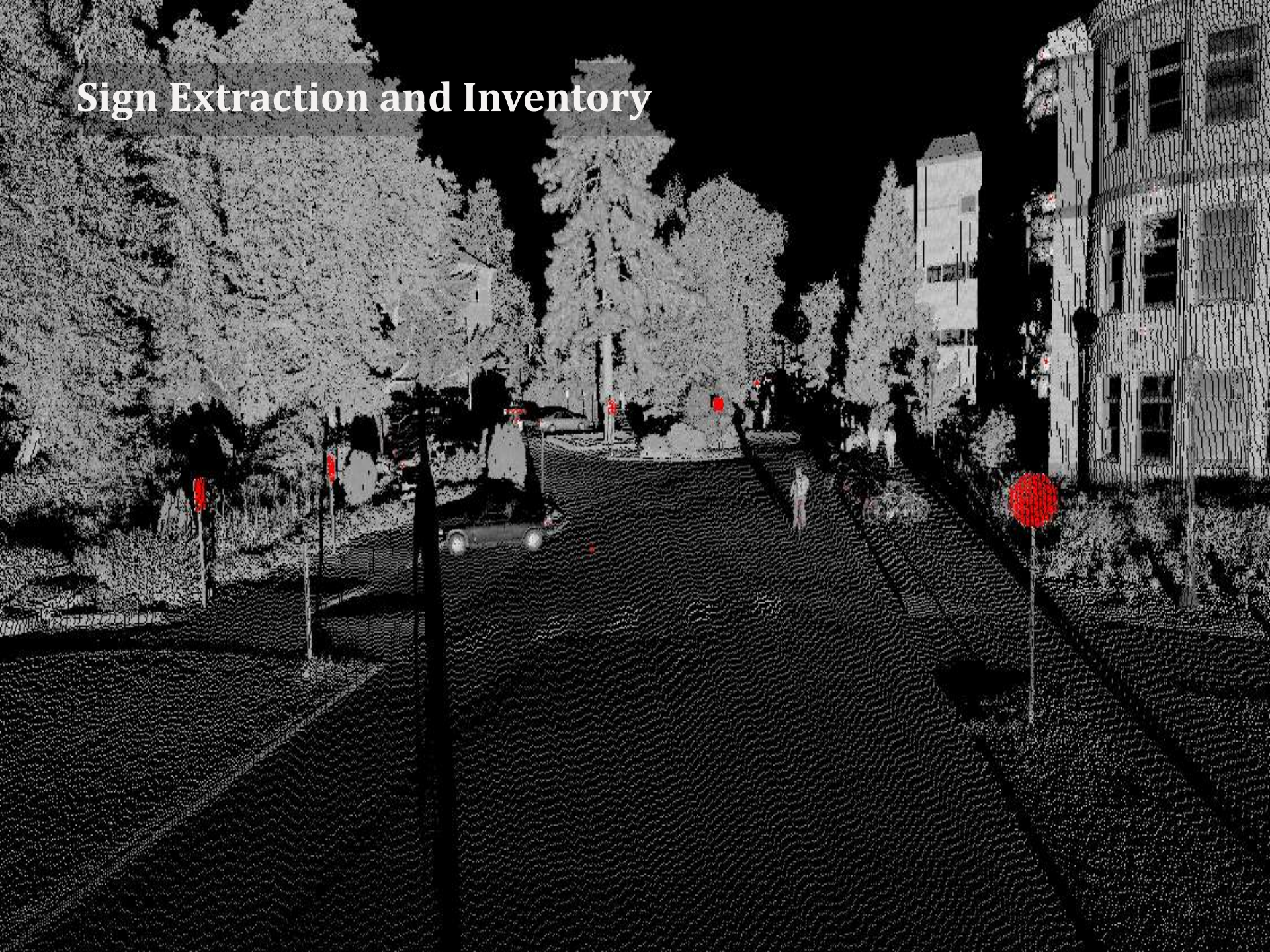


Data Collection Categories

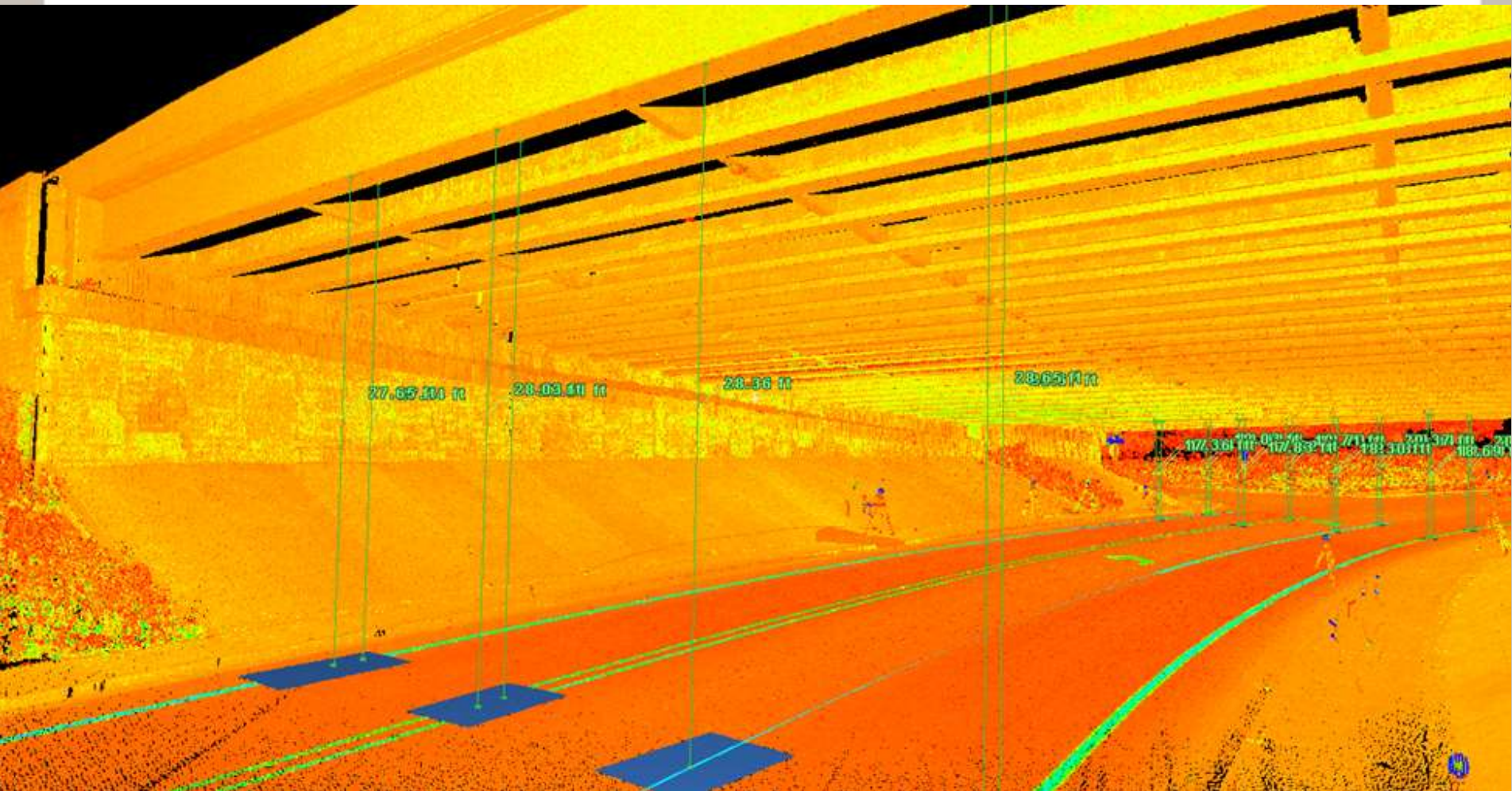


What do you need? What does it cost?

Sign Extraction and Inventory



Bridge Clearances



Conflict Analysis - Endeavour

<https://www.youtube.com/watch?v=i-aOpGvqMPc>

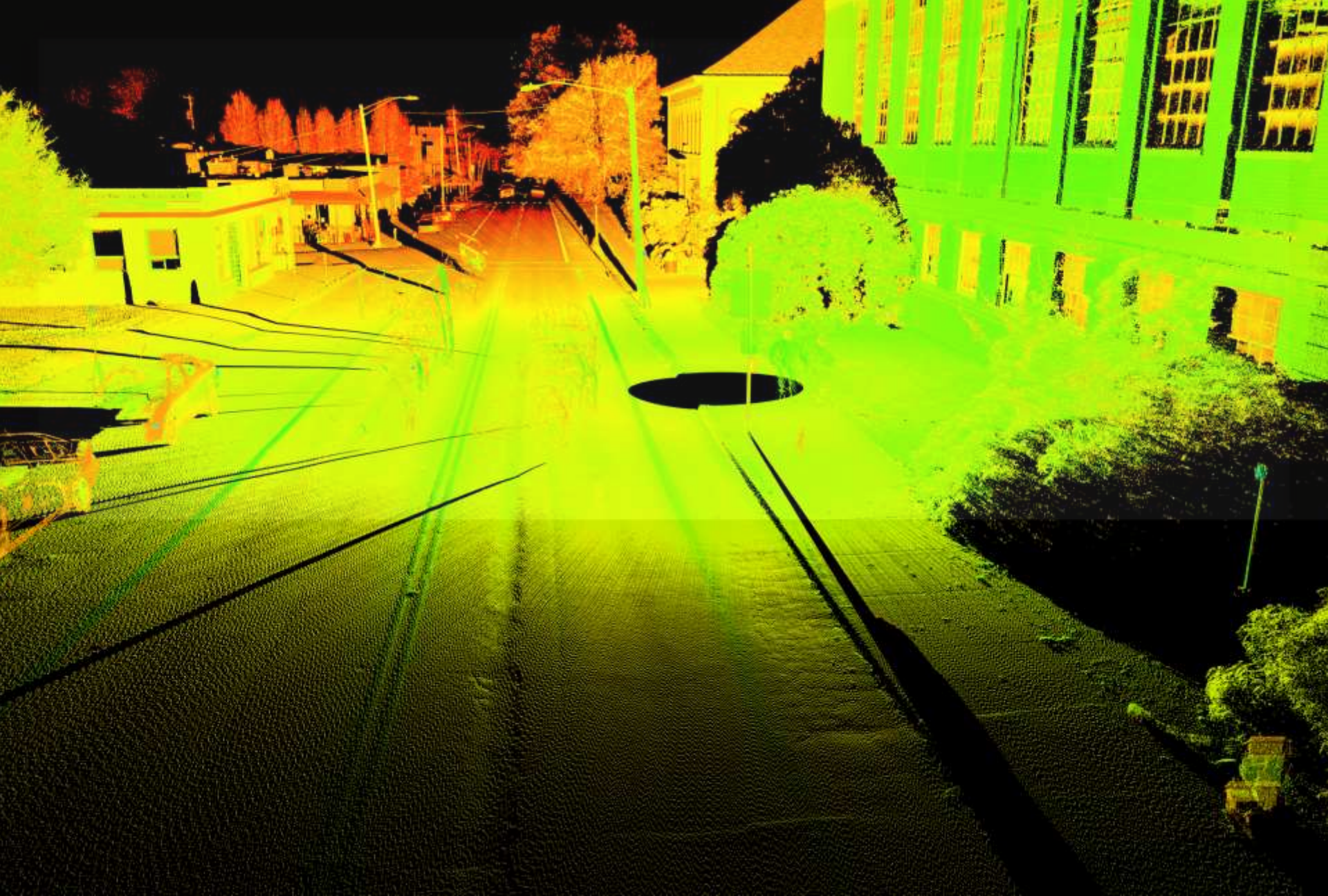


DAVID EVANS
AND ASSOCIATES INC.





Pavement Cracking and deterioration



Rutting

A Platform for Proactive Risk-based Slope Asset Management

LIDAR acquisition and processing

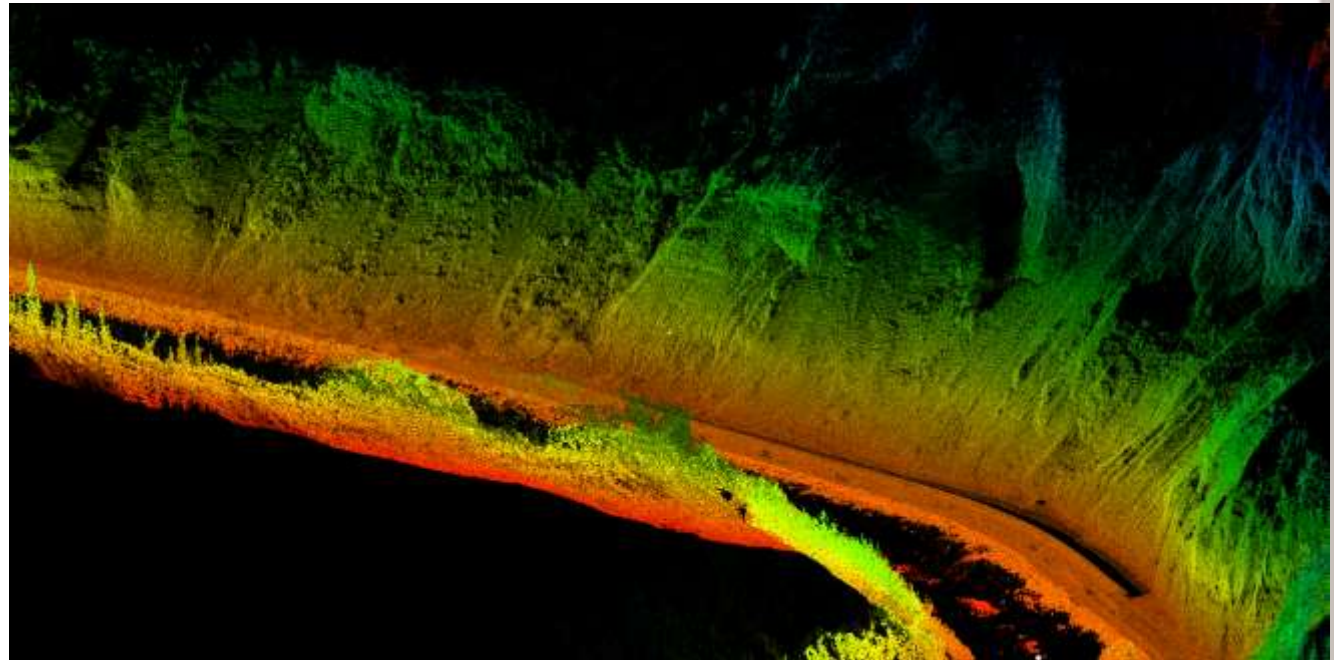
Michael Olsen
Oregon State Univ.

Slope Assessment

Joe Wartman
Lisa Dunham
Univ. of Washington

Risk Assessment

Keith Cunningham
Univ. of Alaska, Fairbanks

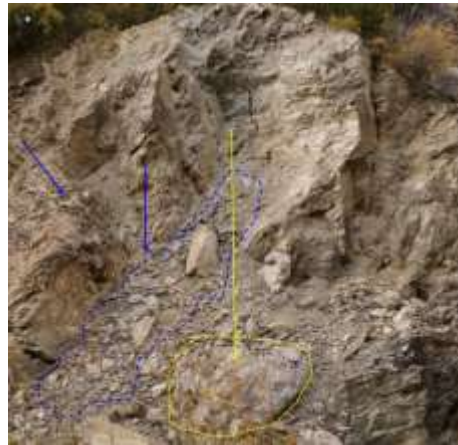


Proactive Risk-based Asset Management

Develop a model that identifies and relates high resolution lidar morphological indices to slope hazard categories which can then be related to risk



LiDAR scanning



Slope Characterization



Determining Risk

Use emerging technologies to create an automated risk classification system

Risk along Highway





Understanding coastal change through terrestrial laser scanning

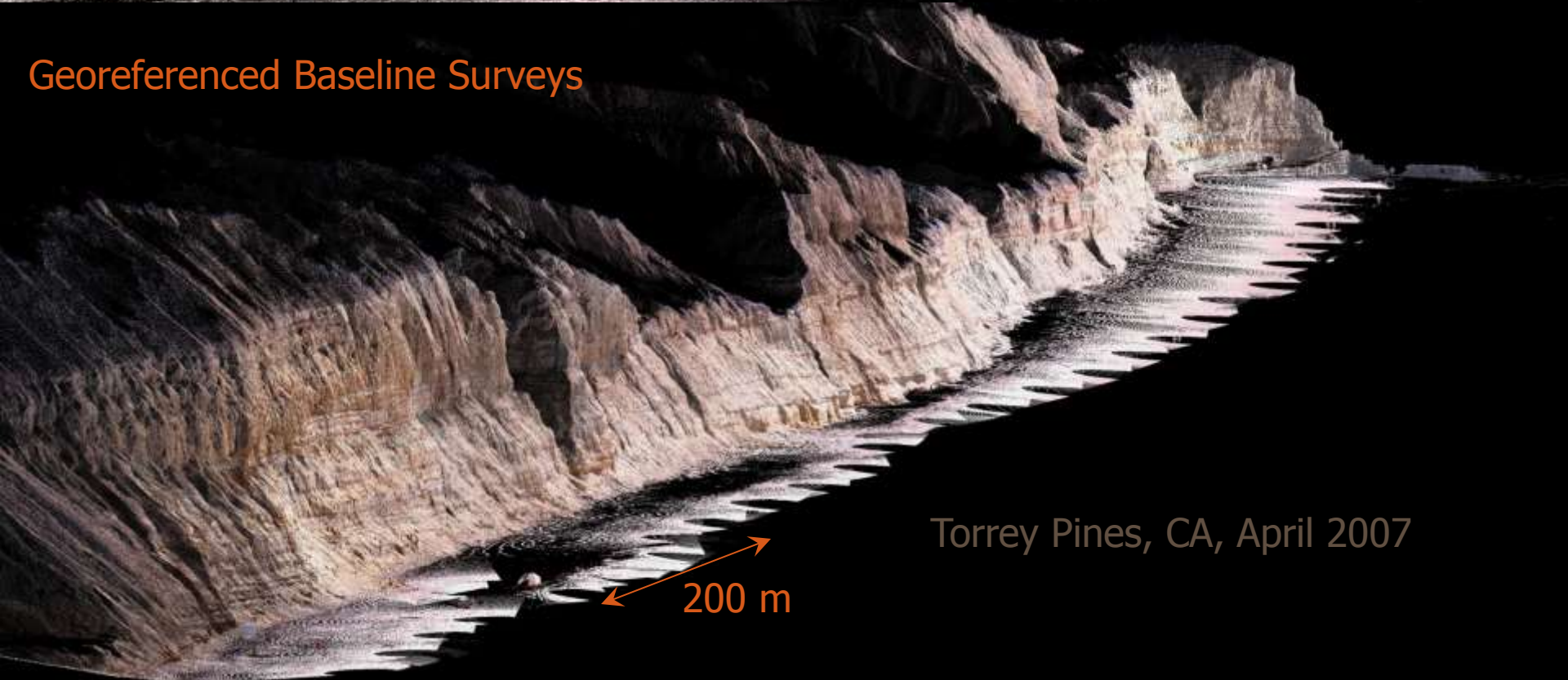
Co-authors: Elizabeth Johnstone, Scott A. Ashford,
Neal Driscoll, Falko Kuester



Encinitas, CA, Dec. 2006

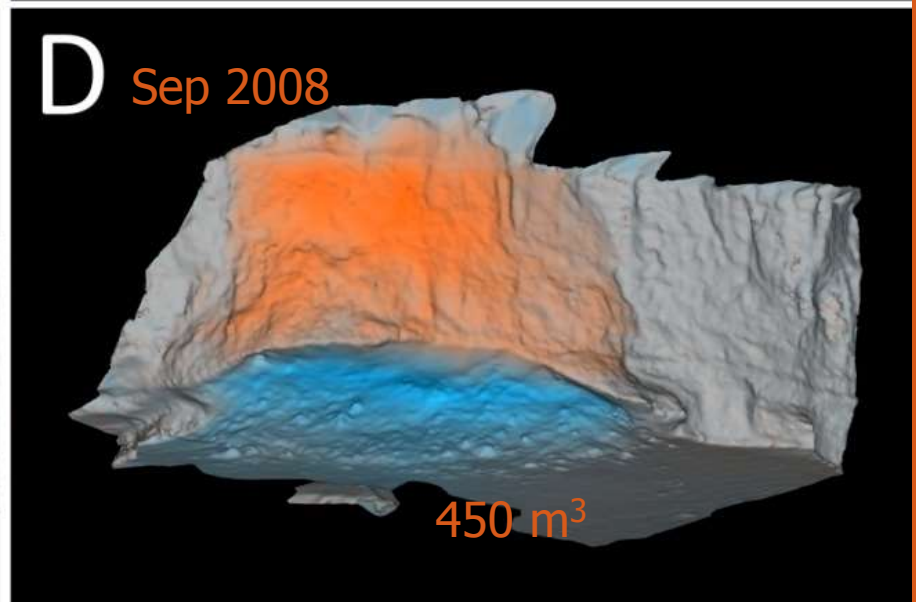
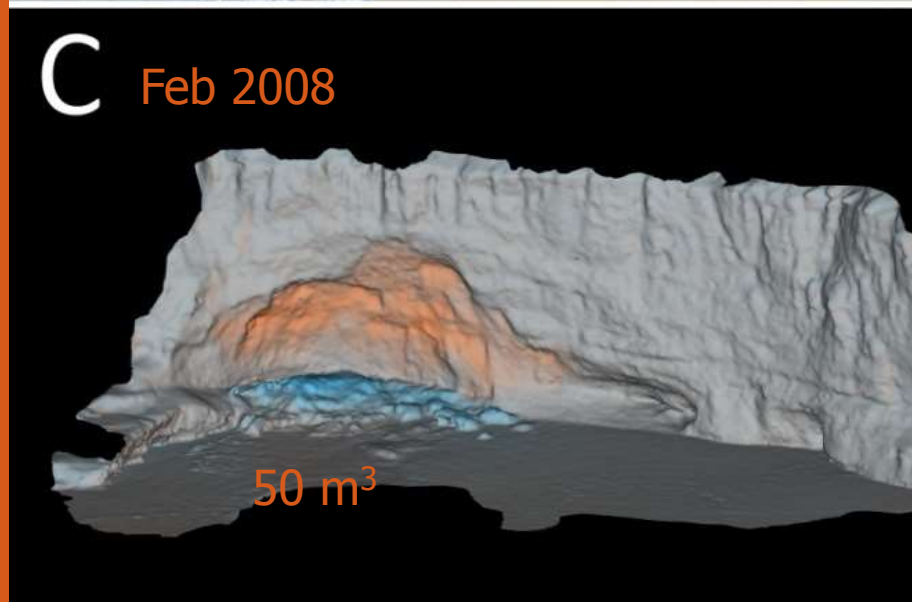
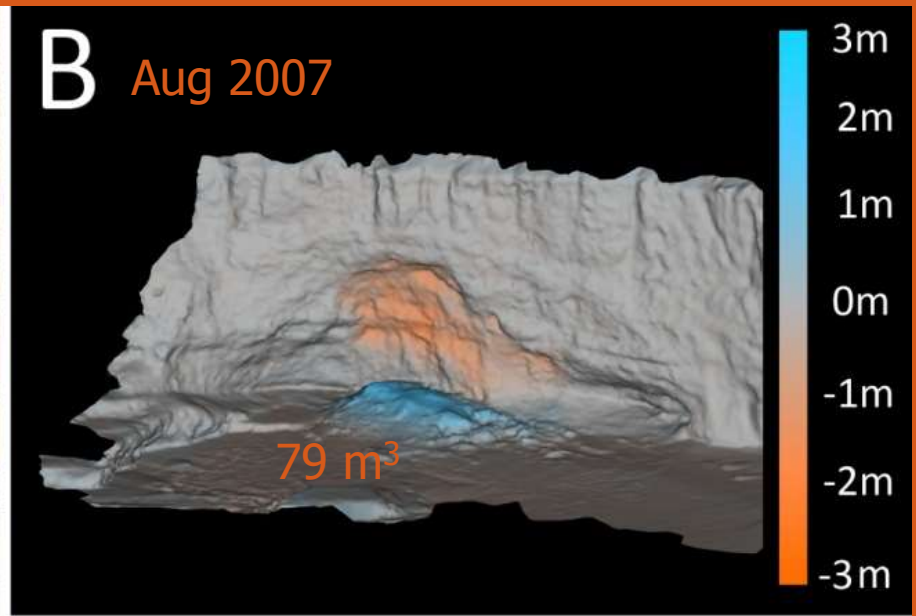
50 m

Georeferenced Baseline Surveys



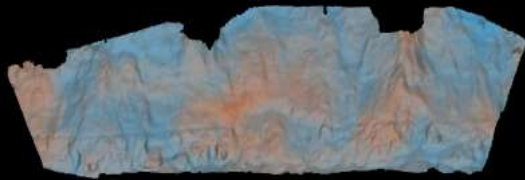
Torrey Pines, CA, April 2007

200 m

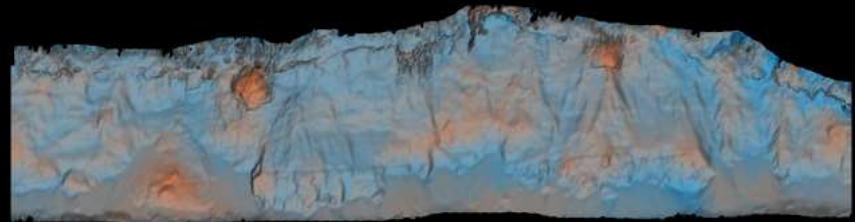


*Change referenced to the November 2006 survey

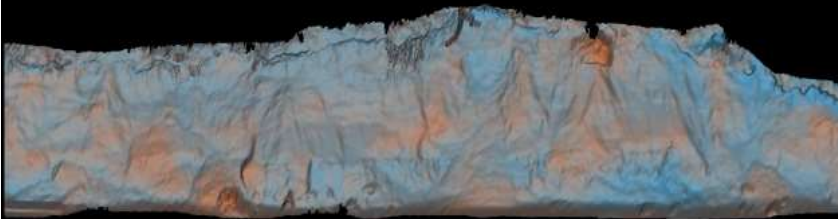
Johnson Creek Landslide, OR



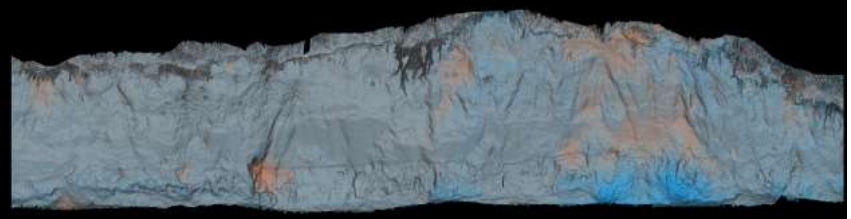
(a) 2004



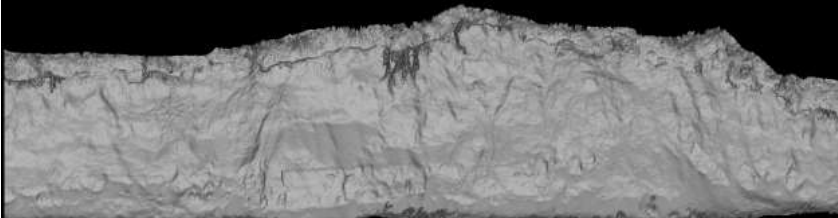
(b) 2006



(c) 2007



(d) 2010



(e) 2011

Advance

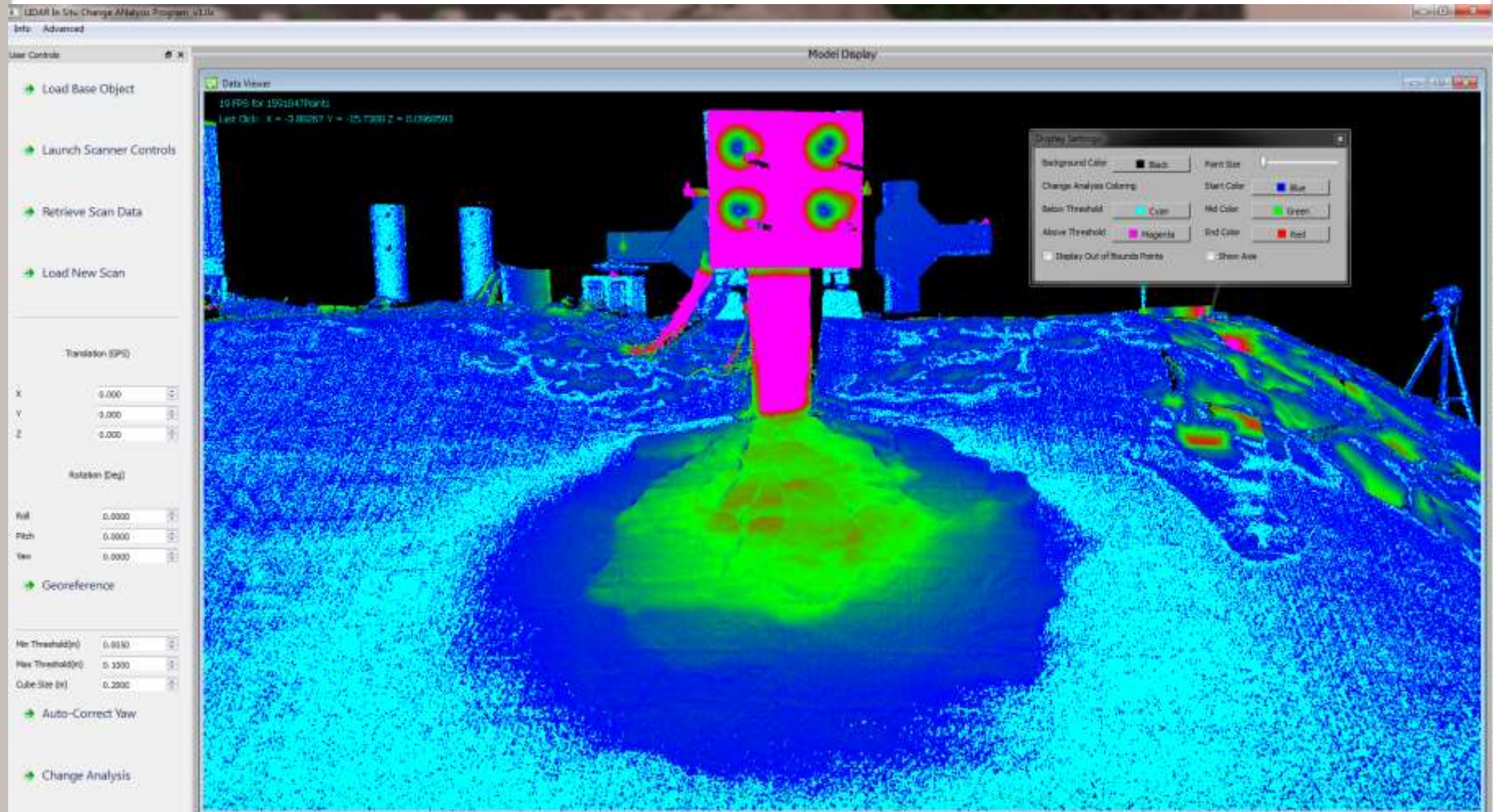
Retreat



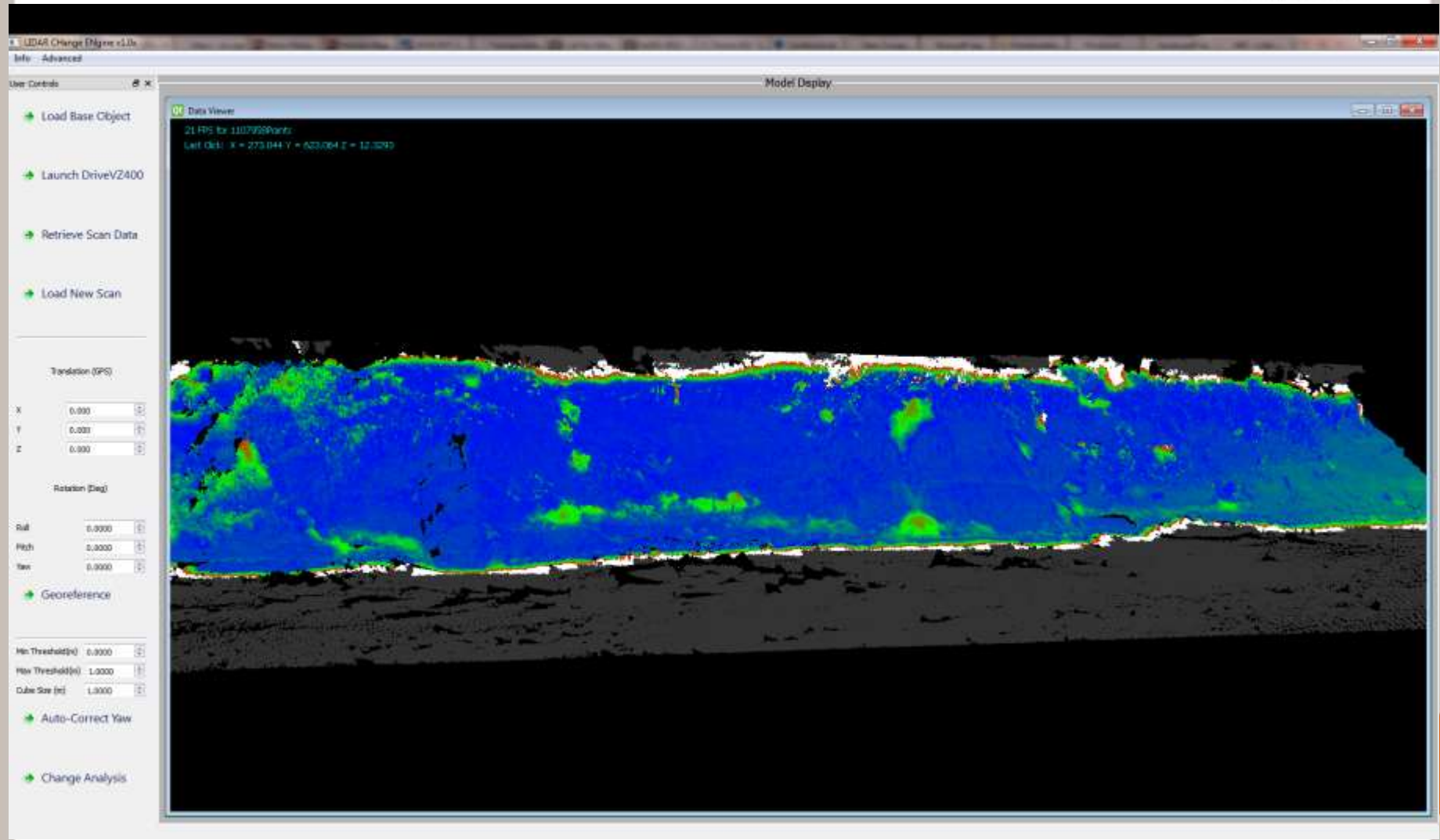
2 m 1 m 0 m -1 m -2 m

(f) Legend

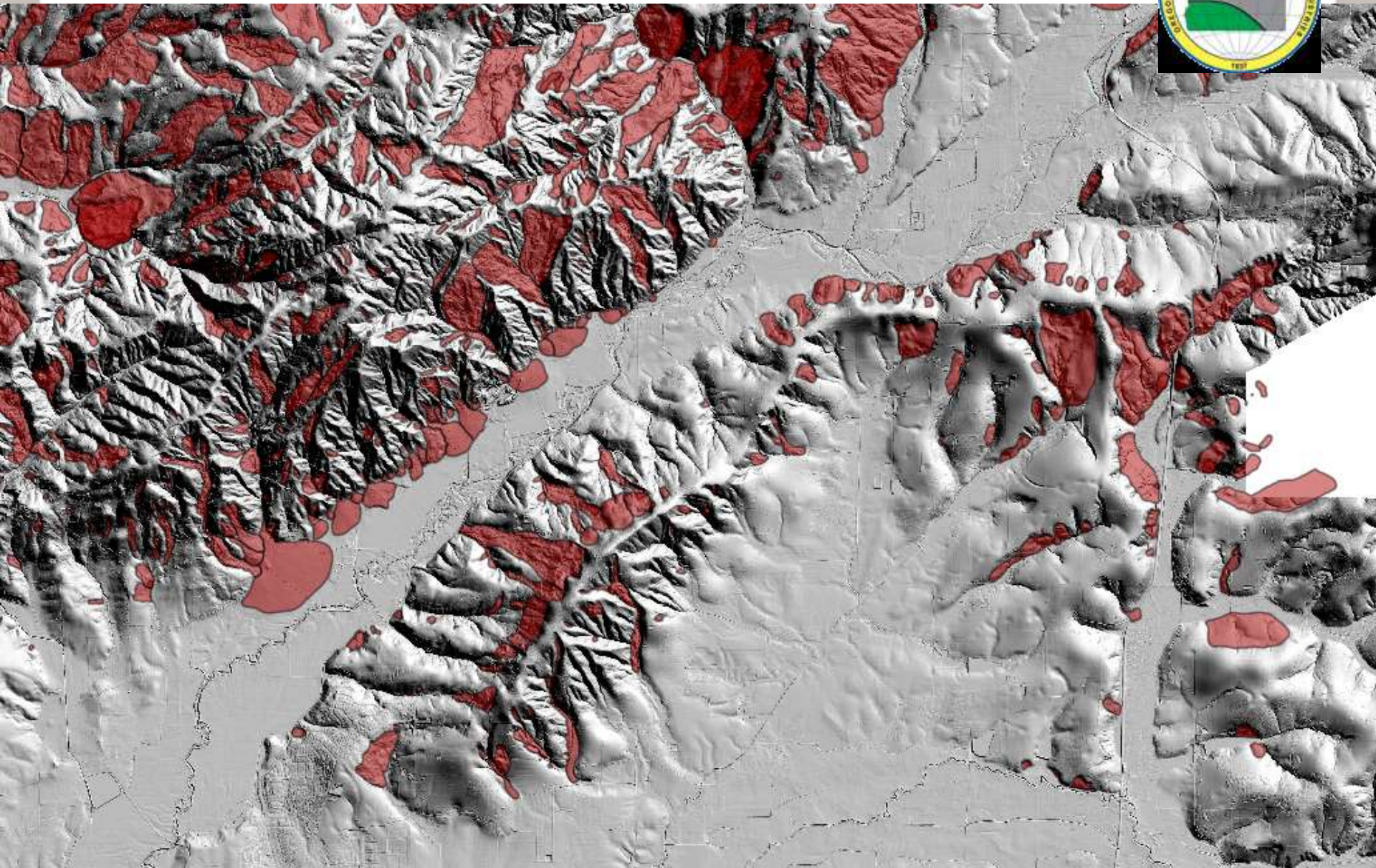
In-Situ Change Detection with lidar

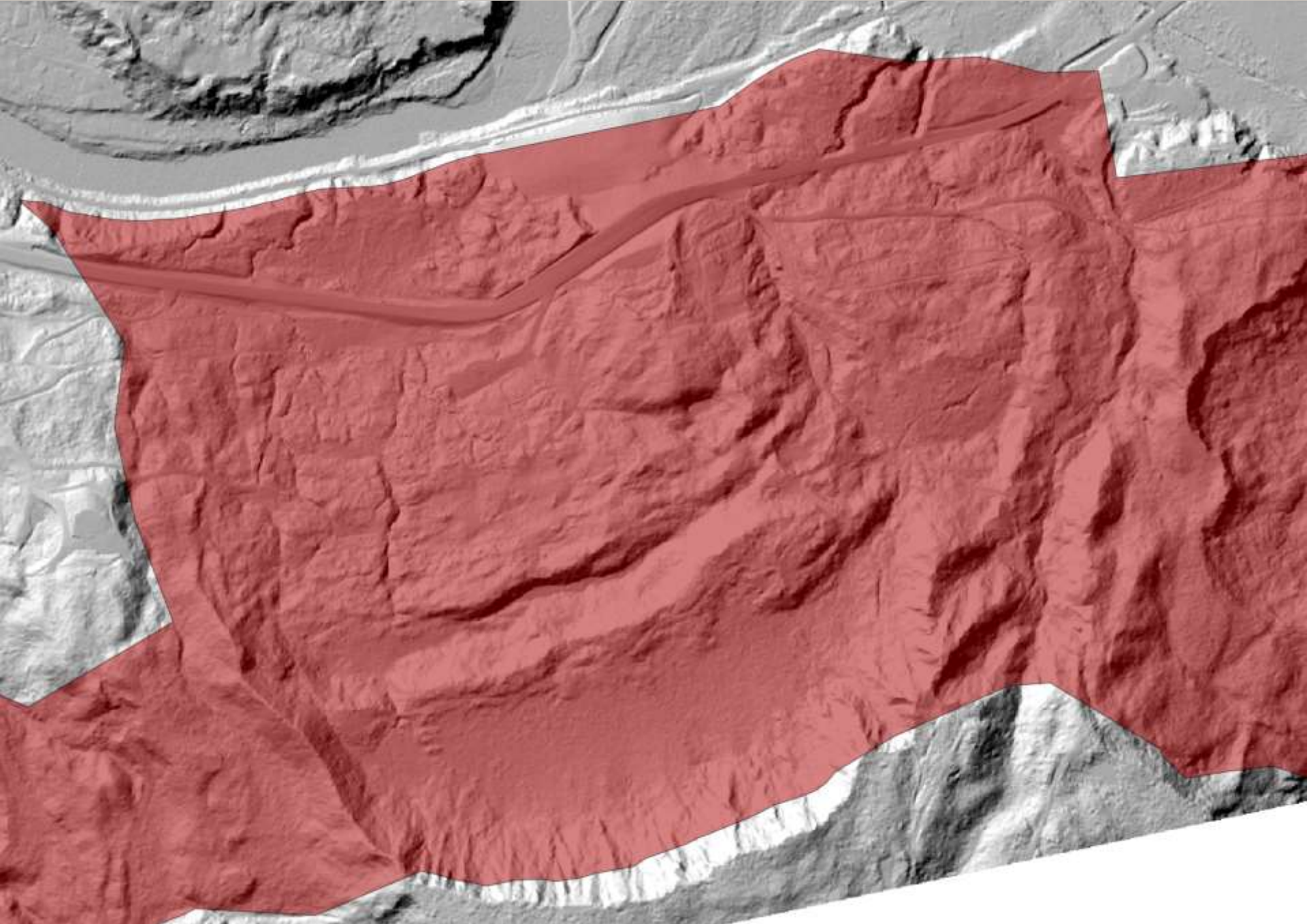


LISCAN (In-Situ Change)



Landslide Inventory- DOGAMI

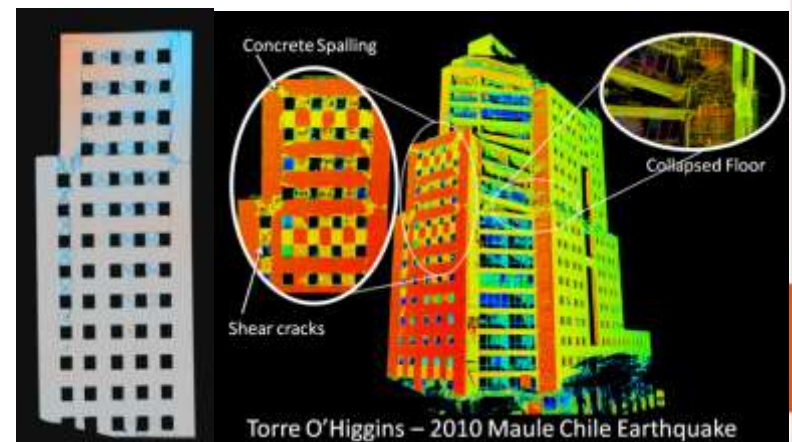
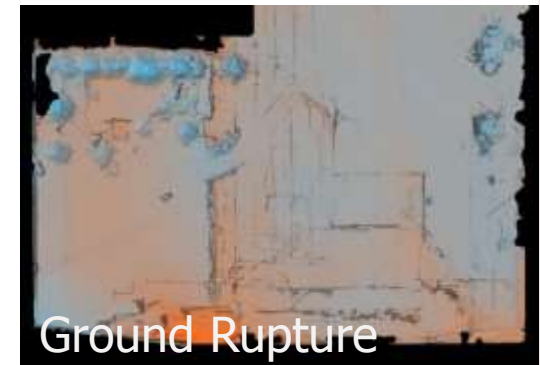
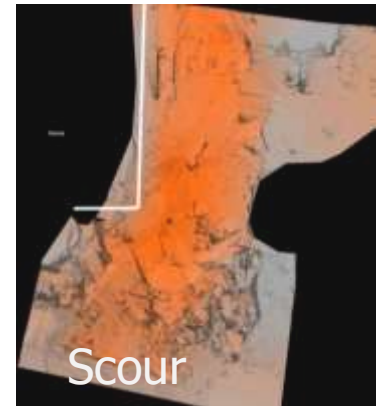




Contour Connection Method

Post EQ/tsunami analyses

- Liquefaction\Lateral spreading
- Landslide\slope stability
- Coastal erosion
- Settlement
- Scour (Depth distribution and volume)
- Bridge Collapse
- Structural Deformations/displacements
- Shear cracking
- Spalled concrete
- Concrete wall blow-out
- Building rotation
- Quay, retaining, sea wall failures
- Surface Rupture



Capturing the Impacts: 3D Scanning after the 2011 Tohoku Earthquake & Tsunami

Michael J. Olsen

Ian N. Robertson

Gary Chock

Lyle P. Carden

Solomon Yim



ASIA AIR SURVEY CO., LTD.

Onagawa Buildings



Point Cloud



Cross Section Measurements



Floor	Lateral Displacement (m)
4 (roof)	0.505
3	0.444
2	0.224
1 ground)	0.000

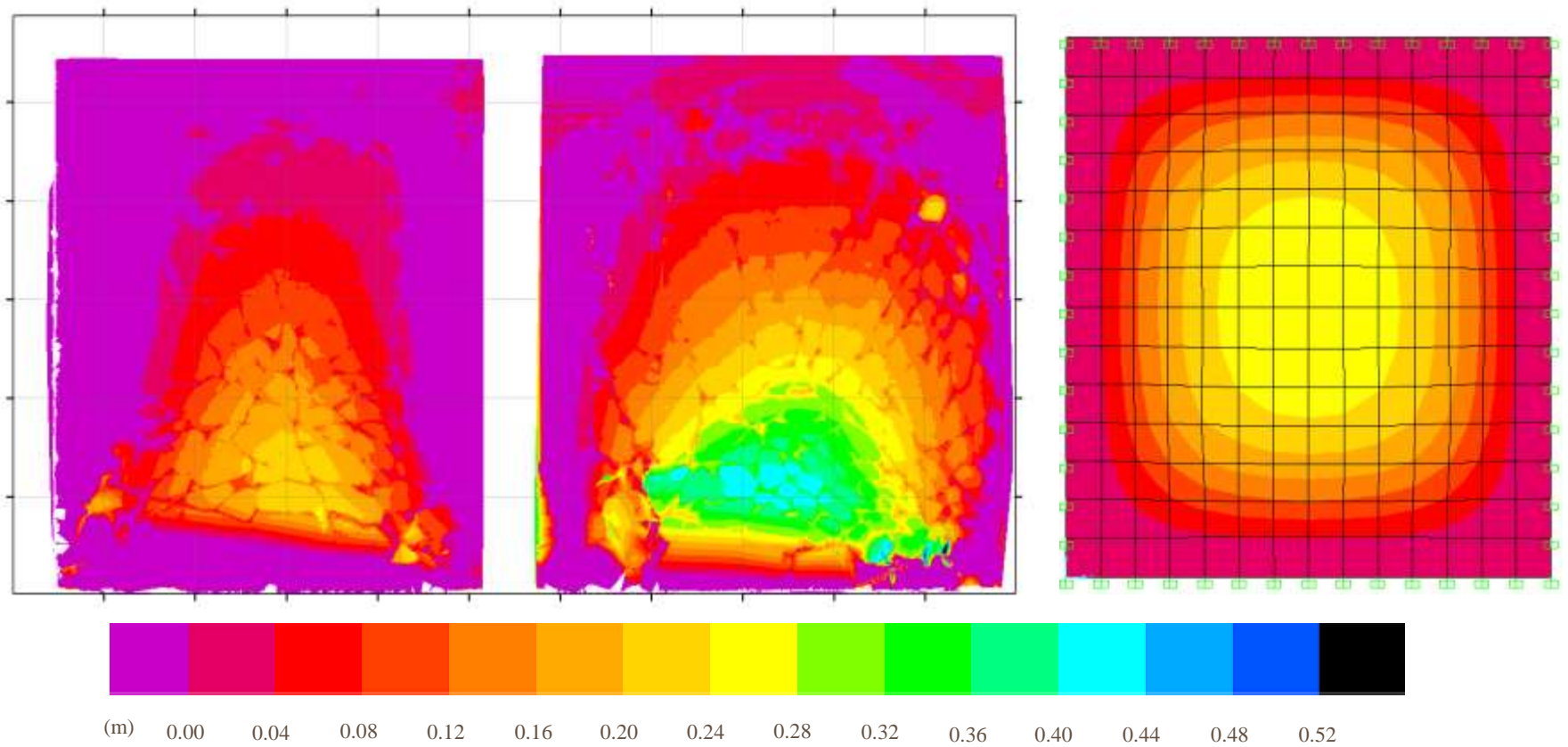
Photograph



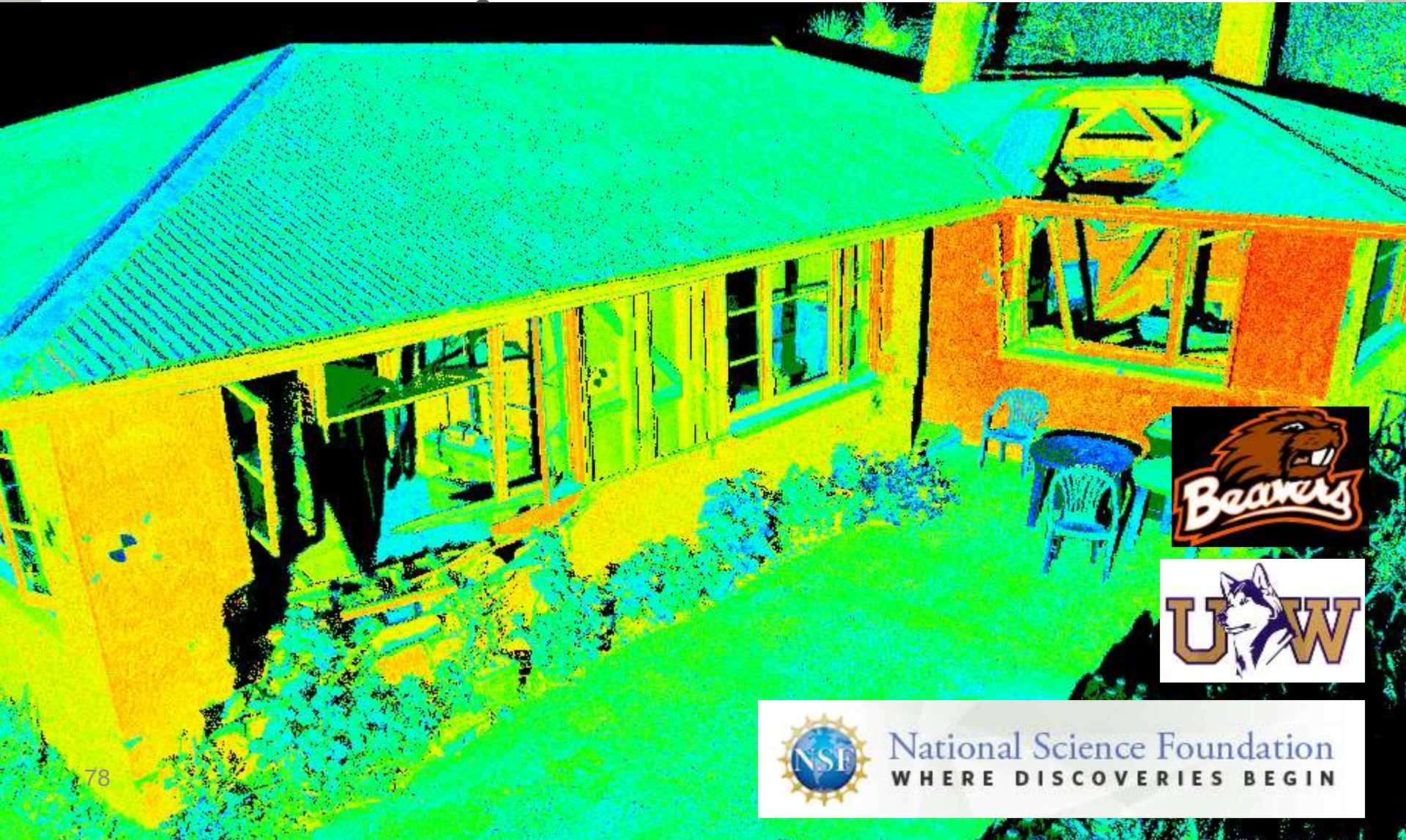
Concrete Warehouse, Onagawa



Wall blow-outs: LIDAR versus FEM.



NSF- RAPID/Collaborative Research: Investigation of the Effects of Rockfall Impacts on Structures During the Christchurch Earthquake Series



National Science Foundation
WHERE DISCOVERIES BEGIN

Lessons learned from TLS in disaster environments

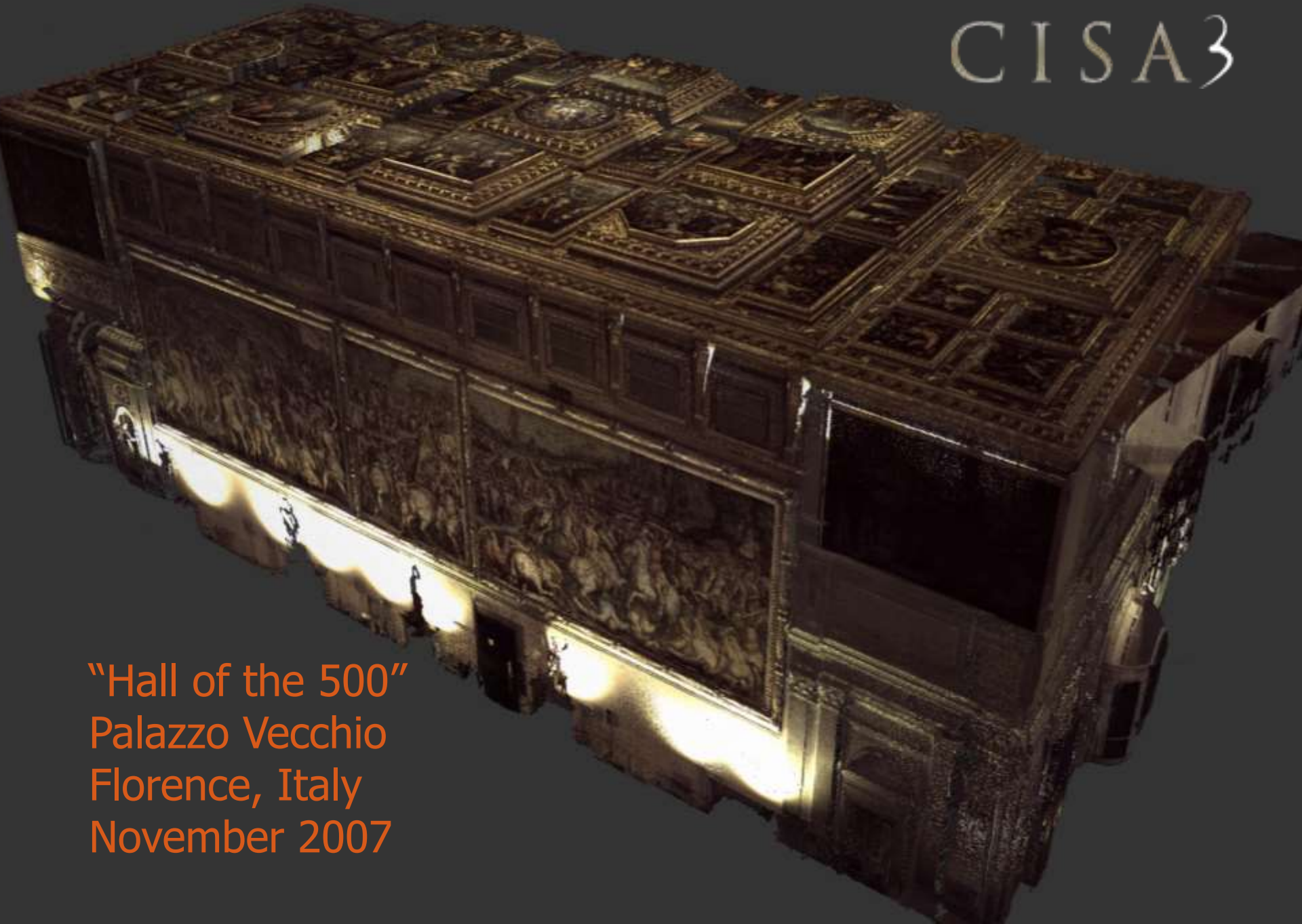
- TLS preserves the data virtually, so you can explore anytime and from any location without safety concerns -> Virtual Time Capsule
- TLS provides data to validate and calibrate numerical models
- For structural analysis, TLS provides more information than can be used in current models
- TLS records vital information regarding surrounding terrain and objects -> puts data in context
- TLS maps the location, distribution, and patterns of deformations compared to relatively few traditional measurements and observations



Balboa Park, San Diego, CA
March 26, 2009

CISA3

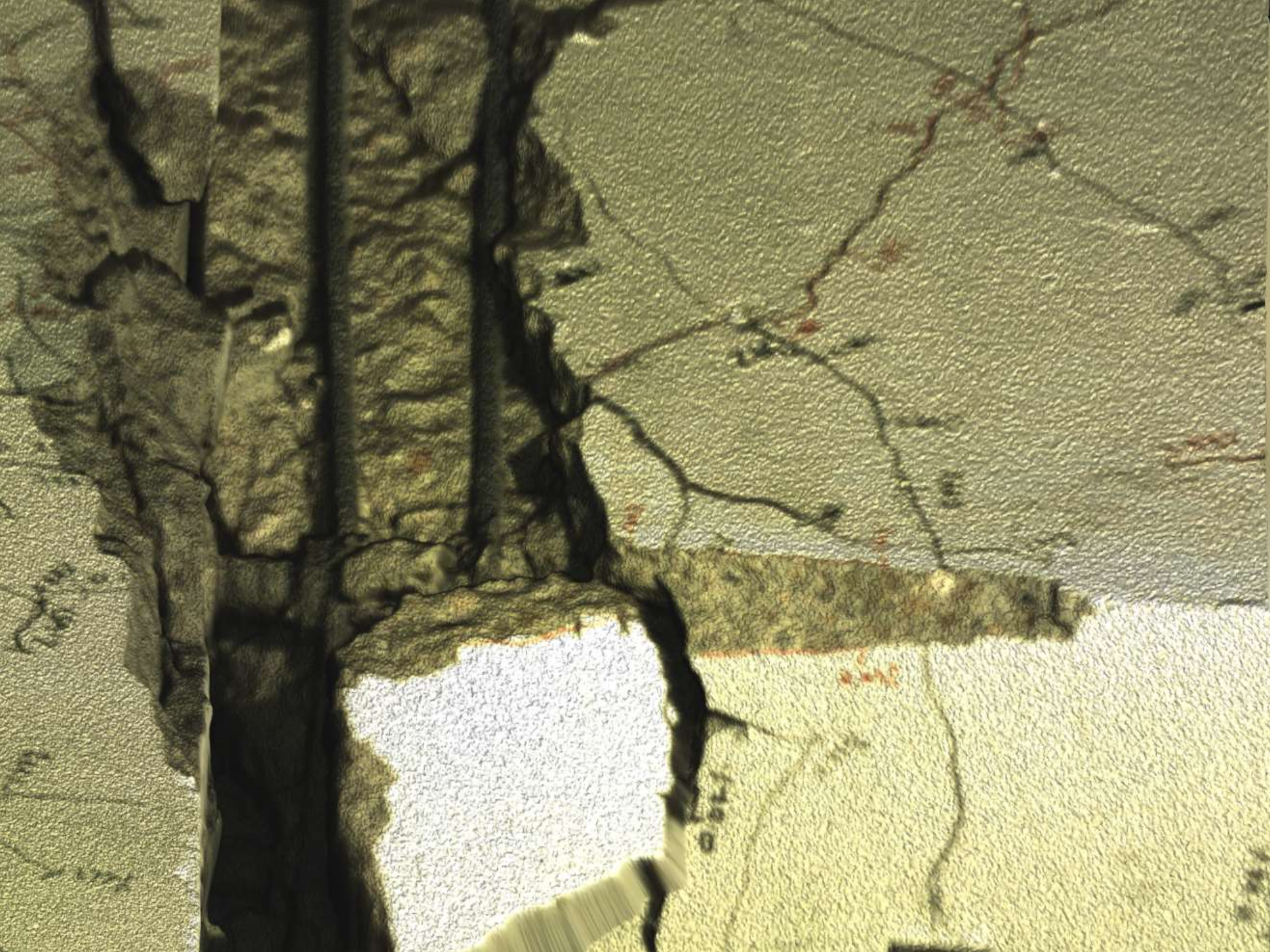
"Hall of the 500"
Palazzo Vecchio
Florence, Italy
November 2007

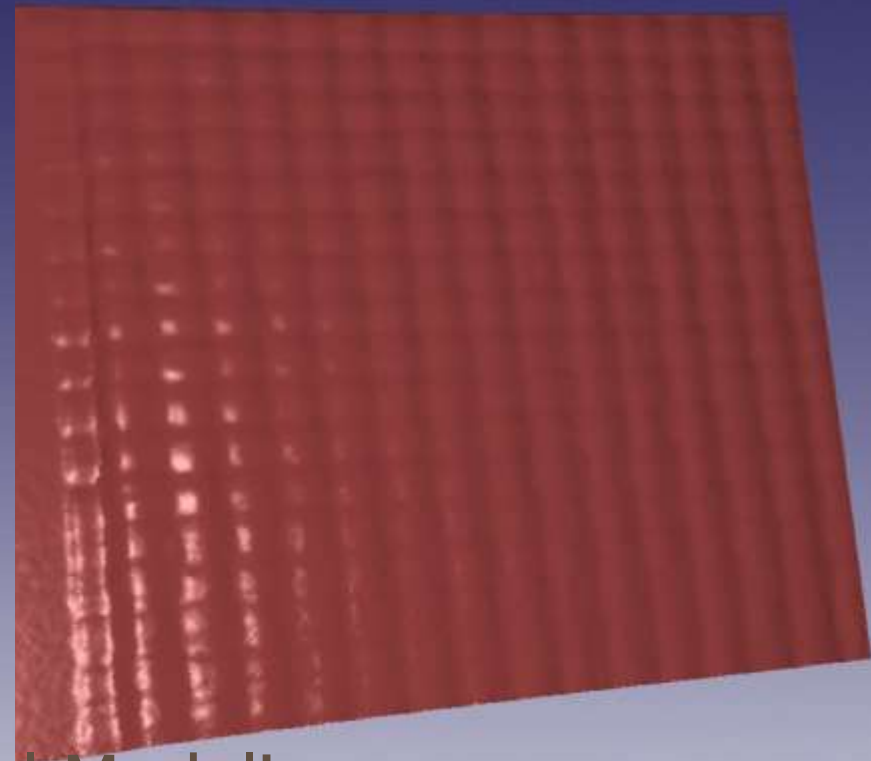
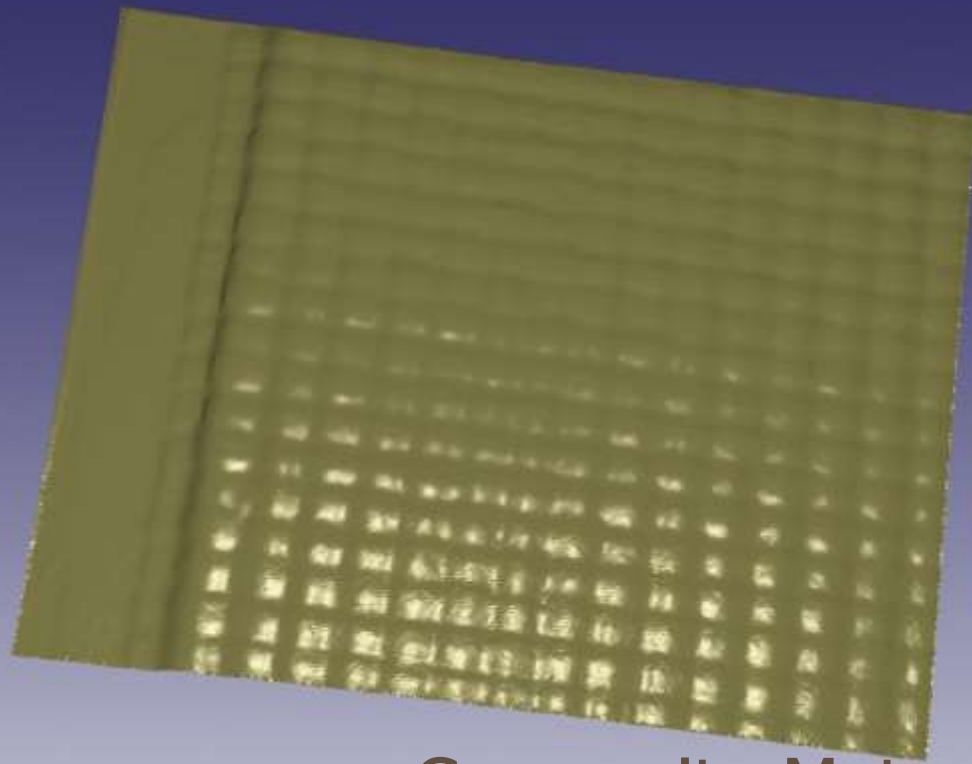






“Hall of the 500” Palazzo Vecchio Florence, Italy





Composite Material Modeling



Value of lidar data

- Fast, accurate, safe way to survey
- Allows us to rapidly record time-constrained data
- Can see processes at scales that they occur
- Provides for more accurate quantification of damage
- Useful for input to develop and verify scientific models
- Captures information that can be continually queried without being present on site (New observations that can be missed in the field)



The Future

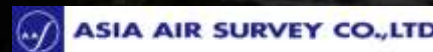
- Hardware advancements
- Software advancements
- Full 3D planning, design and construction
- New, advanced 3D analysis techniques
- Structural monitoring and control
- Simultaneous Location and Mapping (SLAM)
- LIDAR data across the country
- (1-2m resolution vs 30 m)
- Handheld scanning/UAS

Acknowledgements



CISA3

Irwin and Joan Jacobs



UCSD Chancellor's
Interdisciplinary Fund

Neal Driscoll's SIO Lab
Falko Kuester's GRAVITY lab



Need more info?



Questions for discussion?

You know what you guys should get? An ATV!!!!

Is that the Mars Rover?

When will the aliens arrive?

Do you have a concession stand in there? I'll take a taco!!

Hi Wall-E!

How much did that wagon cost?

Can you beam me up, Scotty?

I don't need a computa, I can use my hand as a laser, right?

Well, now I'll go to bed less stupid, right?

Wanna see my geiods?

Are you communicating with the mothership?

Are you sending a satellite around the moon?

That looks suspiciously like a robot....is it?

Is that a submarine?

I was wondering if you were going to travel around the world in that thing, are you?

Do you keep your dollies in there? Can I play with them?

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